

Using iterated learning to reveal biases for well-structured meanings in language

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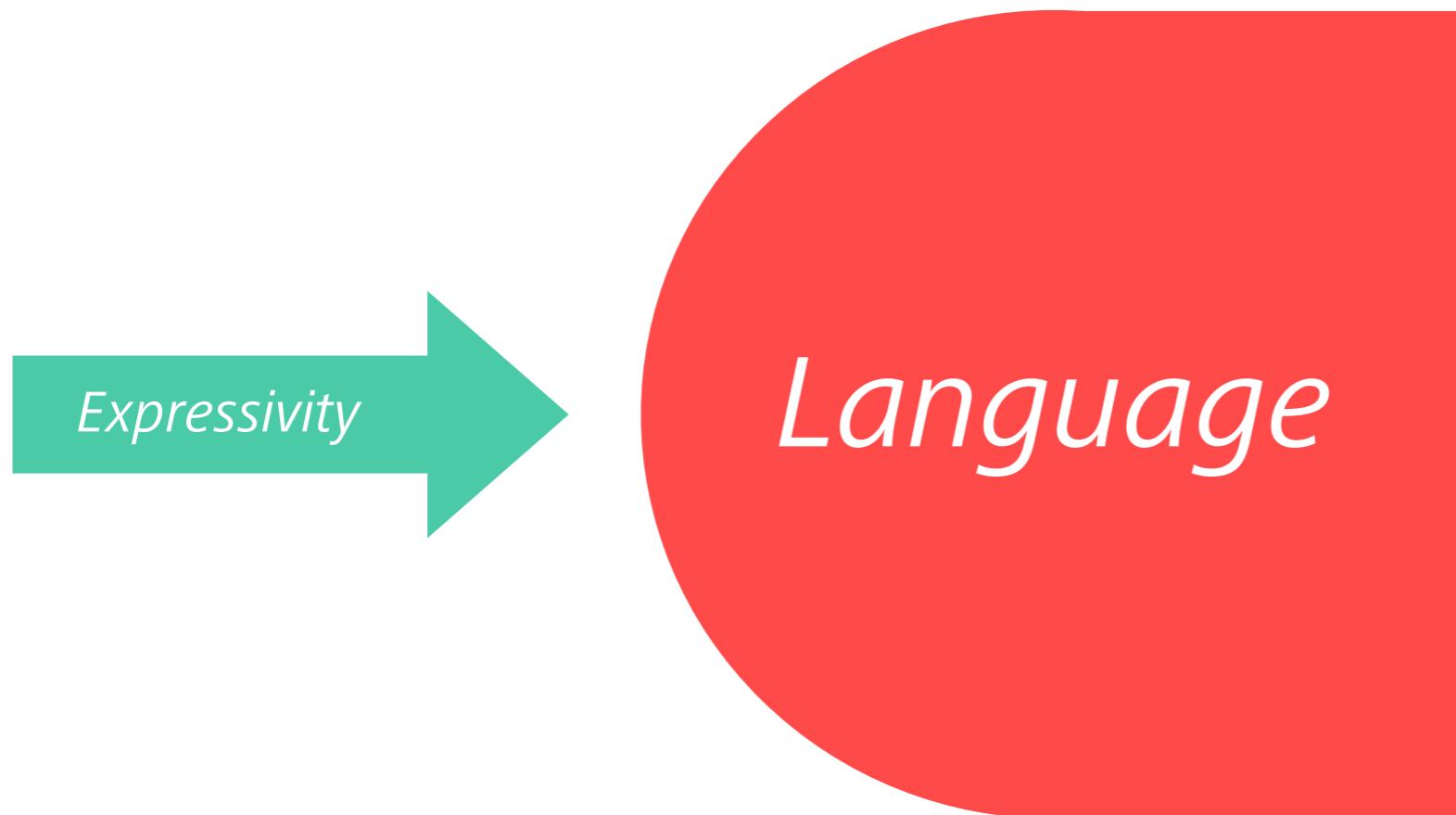
*Linguistics and English Language
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What shapes language?



Language

What shapes language?



What shapes language?



Kirby, Tamariz, Cornish, & Smith, 2015, *Cognition*

What shapes language?



Kirby, Tamariz, Cornish, & Smith, 2015, *Cognition*

Kemp & Regier, 2012, *Science*

What shapes language?



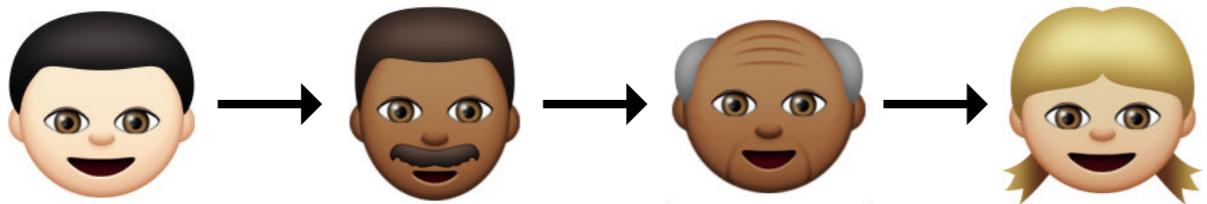
Kirby, Tamariz, Cornish, & Smith, 2015, *Cognition*

Kemp & Regier, 2012, *Science*

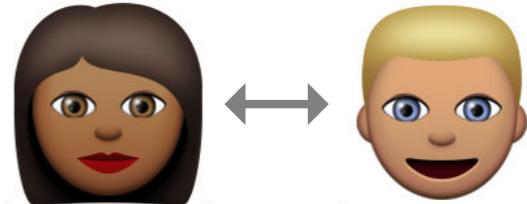
Gabelentz, 1901

Models of learning vs communication

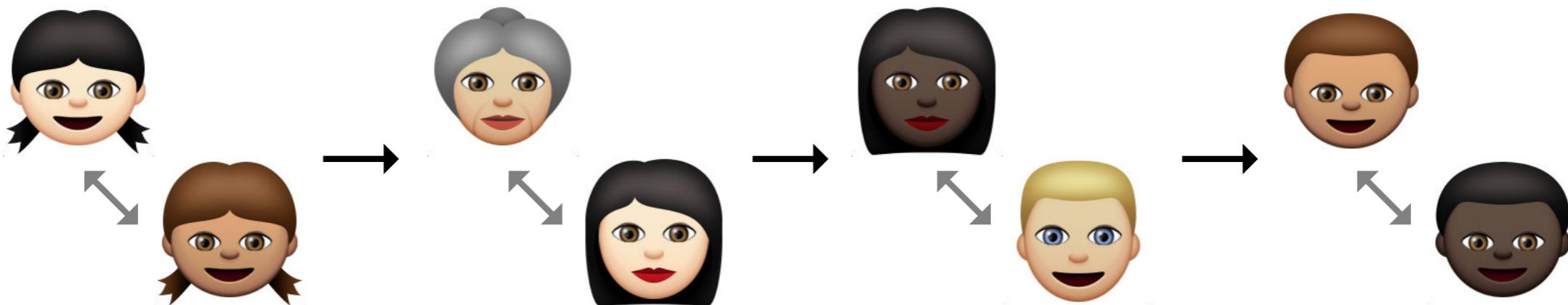
Transmission chain



Dyadic interaction

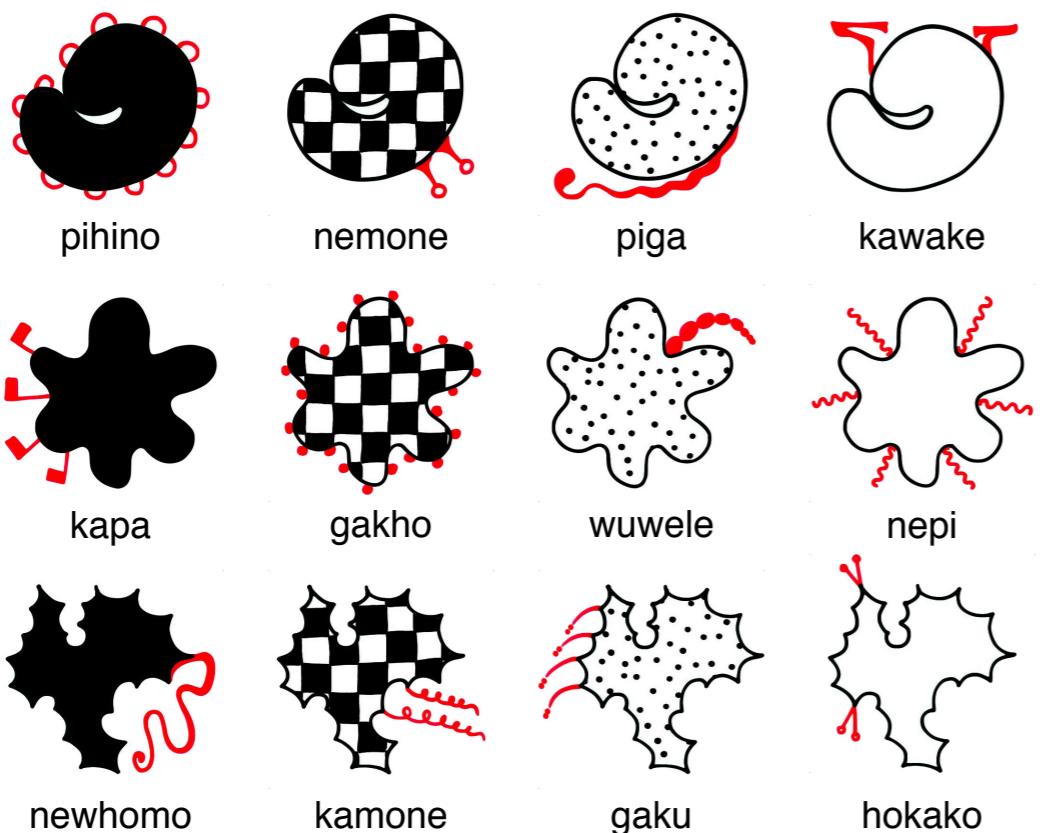


Transmission chain with dyadic interaction

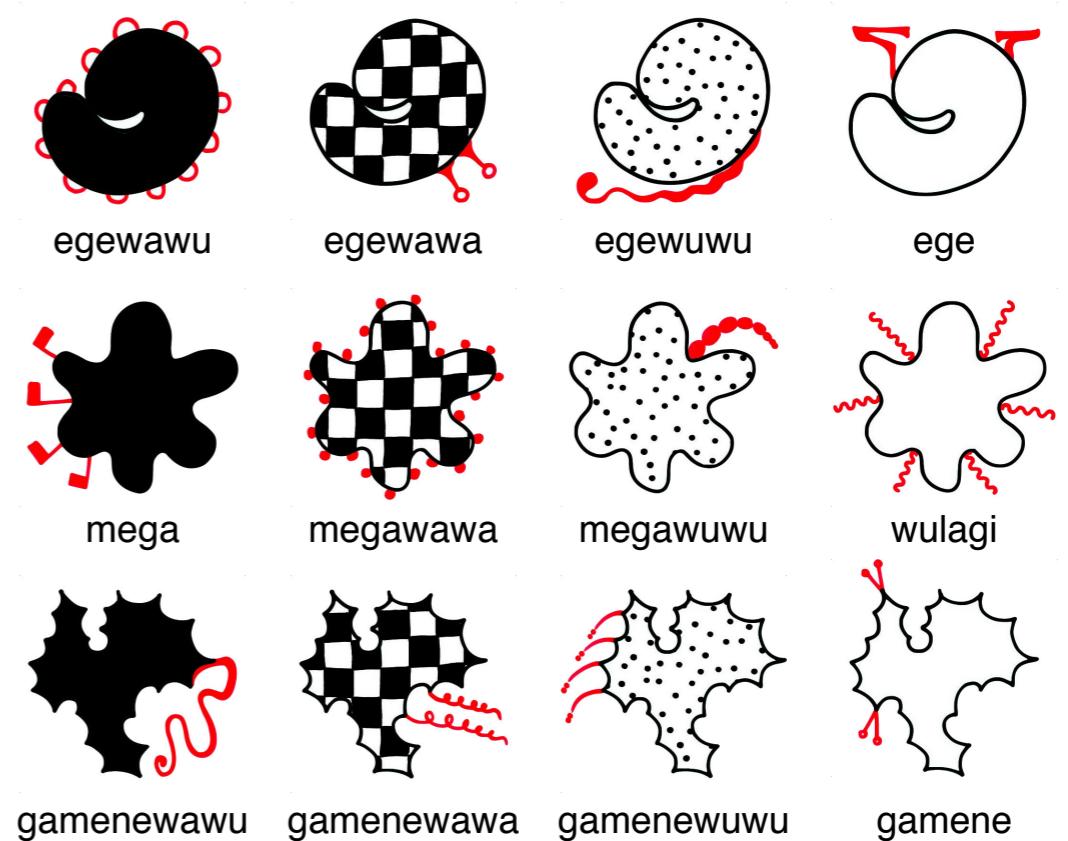


Learning vs communication

Dyadic interaction



Transmission chain with dyadic interaction



*How do learning and
communication shape the
structure of semantic
categories?*

Previous work

Carr, J. W., Smith, K., Cornish, H., & Kirby, S. (2016). The cultural evolution of structured languages in an open-ended, continuous world. *Cognitive Science*. doi:10.1111/cogs.12371

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The Cultural Evolution of Structured Languages in an Open-Ended, Continuous World

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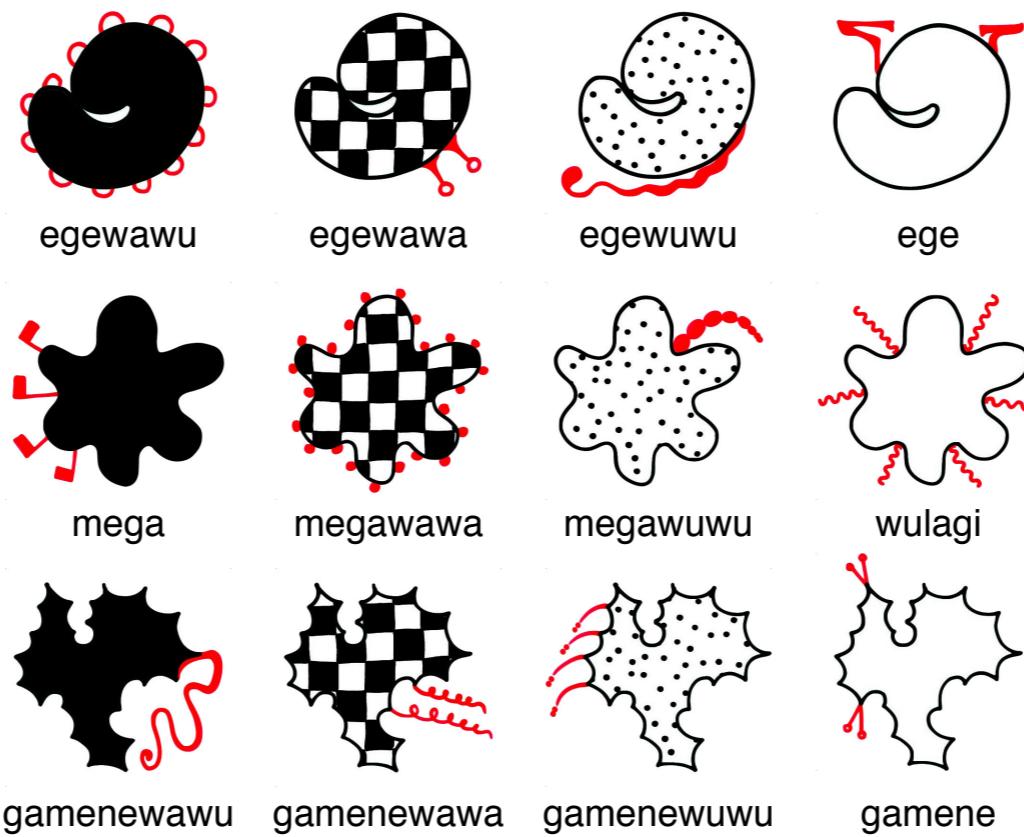
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Abstract
Language maps signals onto meanings through the use of two distinct types of structure. First, the space of meanings is discretized into categories that are shared by all users of the language. Second, the signals employed by the language are compositional: The meaning of the whole is a function of its parts and the way in which those parts are combined. In three iterated learning experiments using a vast, continuous, open-ended meaning space, we explore the conditions under which both structured categories and structured signals emerge *ex nihilo*. While previous experiments have been limited to either categorical structure in meanings or compositional structure in signals, these experiments demonstrate that when the meaning space lacks clear preexisting boundaries, more subtle morphological structure that lacks straightforward compositionality—as found in natural languages—may evolve as a solution to join pressures from learning and communication.

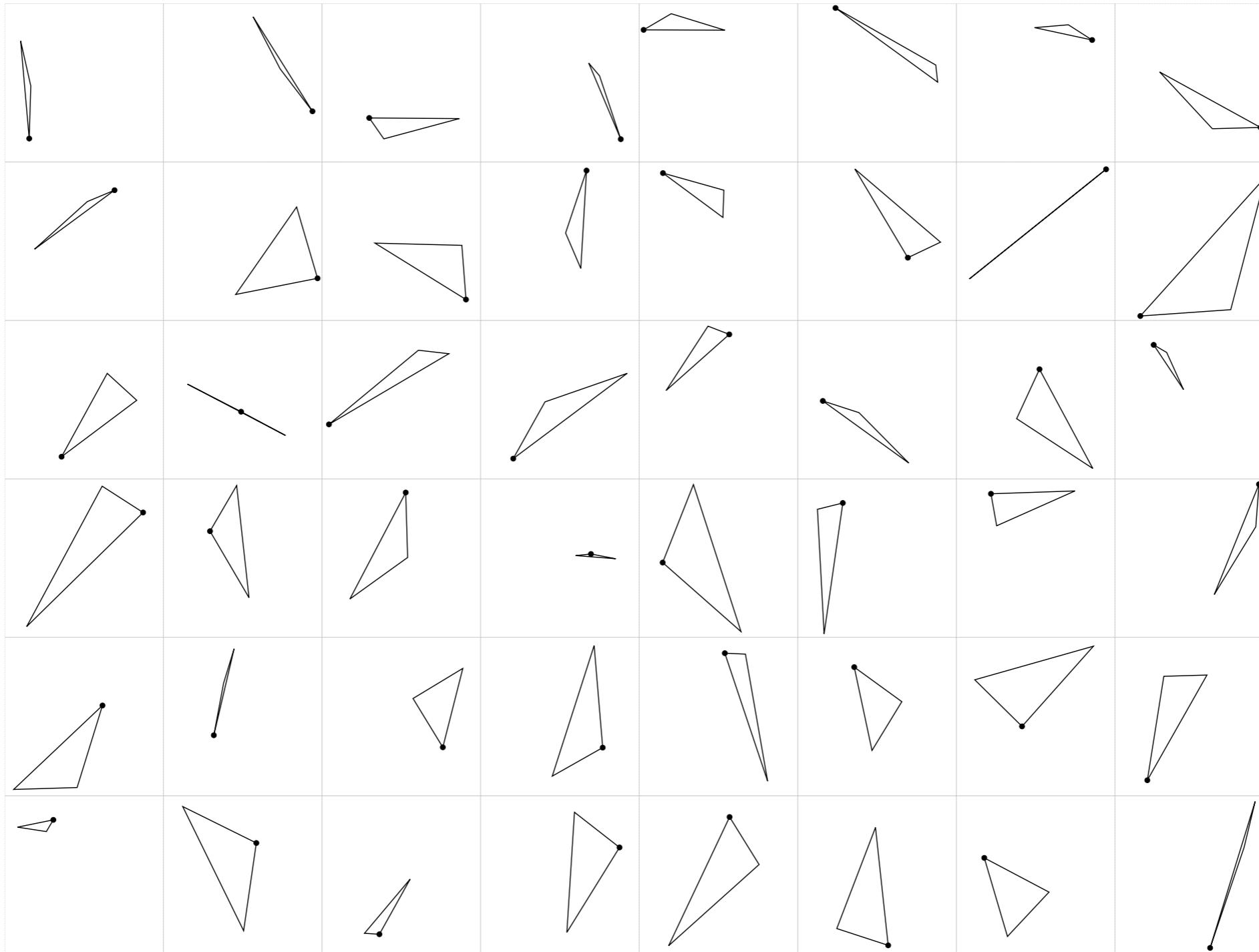
Keywords: Categorization; Communication; Compositionality; Cultural evolution; Iterated learning; Language evolution; Sound symbolism

1. Introduction

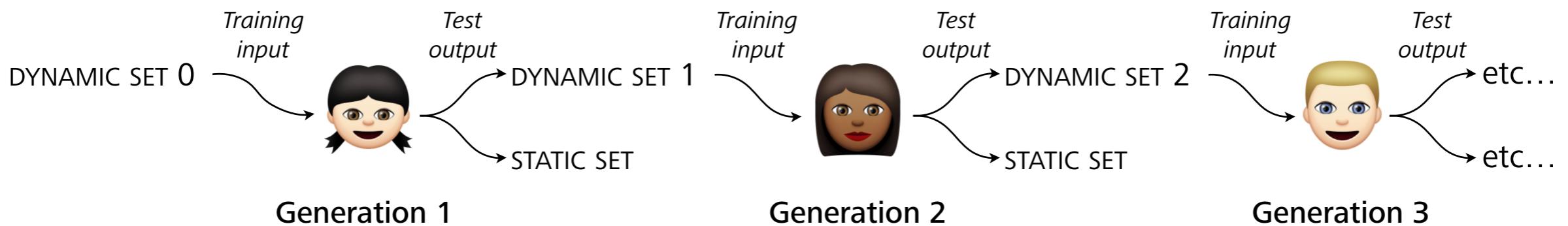
Discrete meaning space



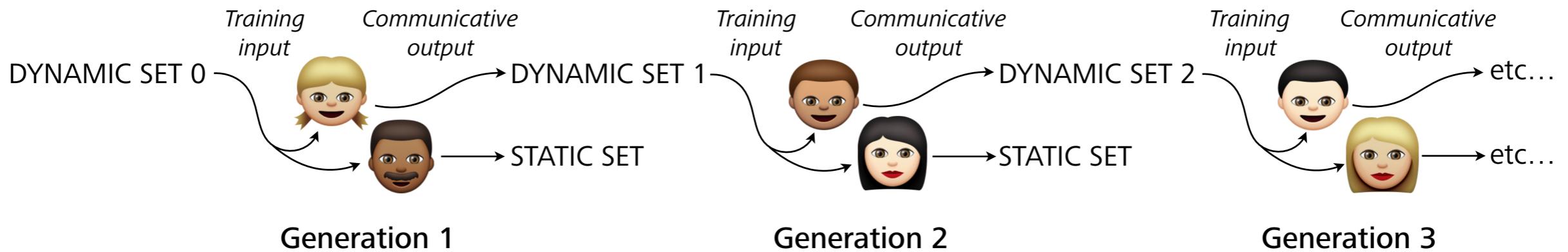
Open-ended meaning space



Experiment 1



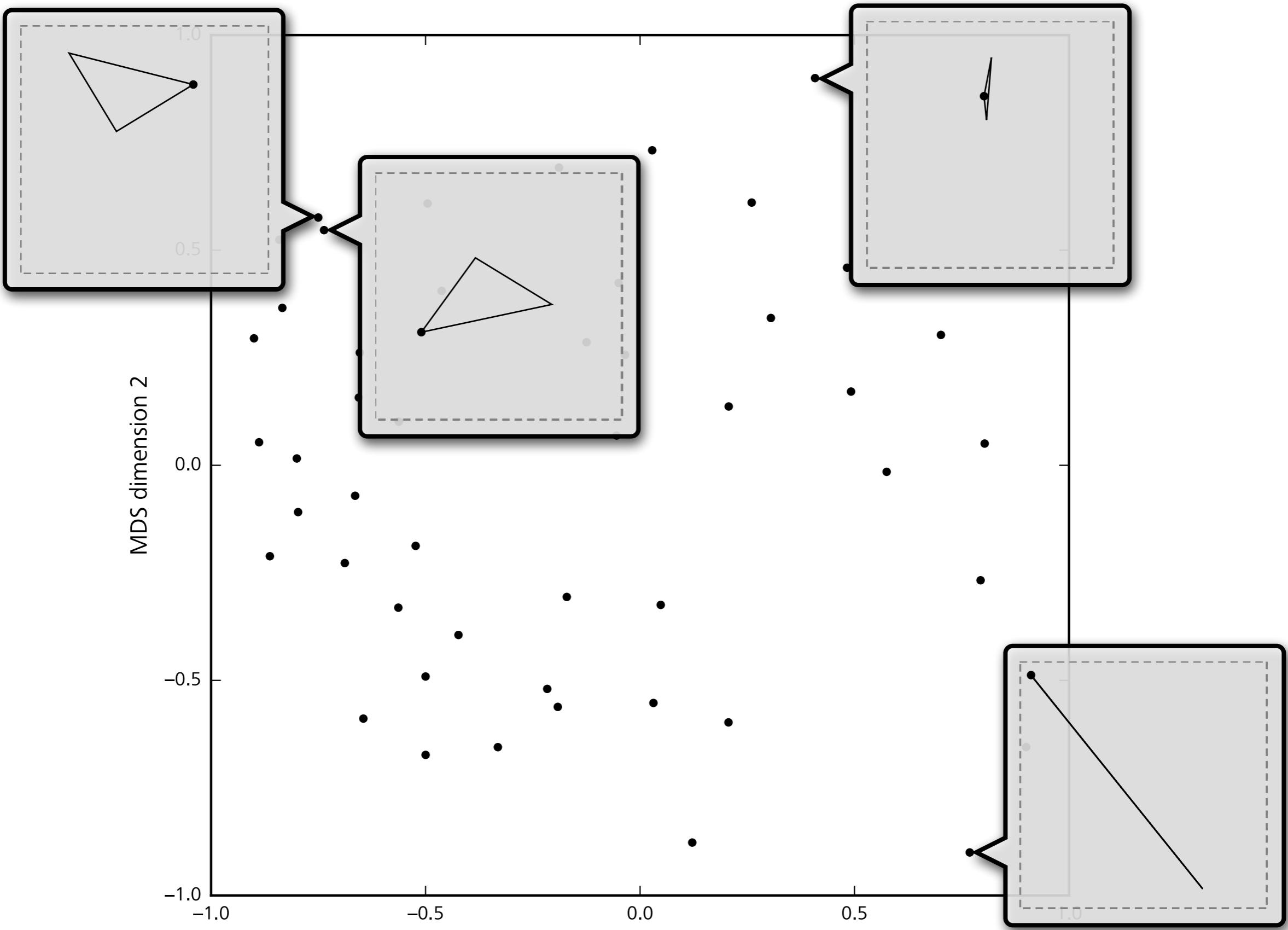
Experiment 2

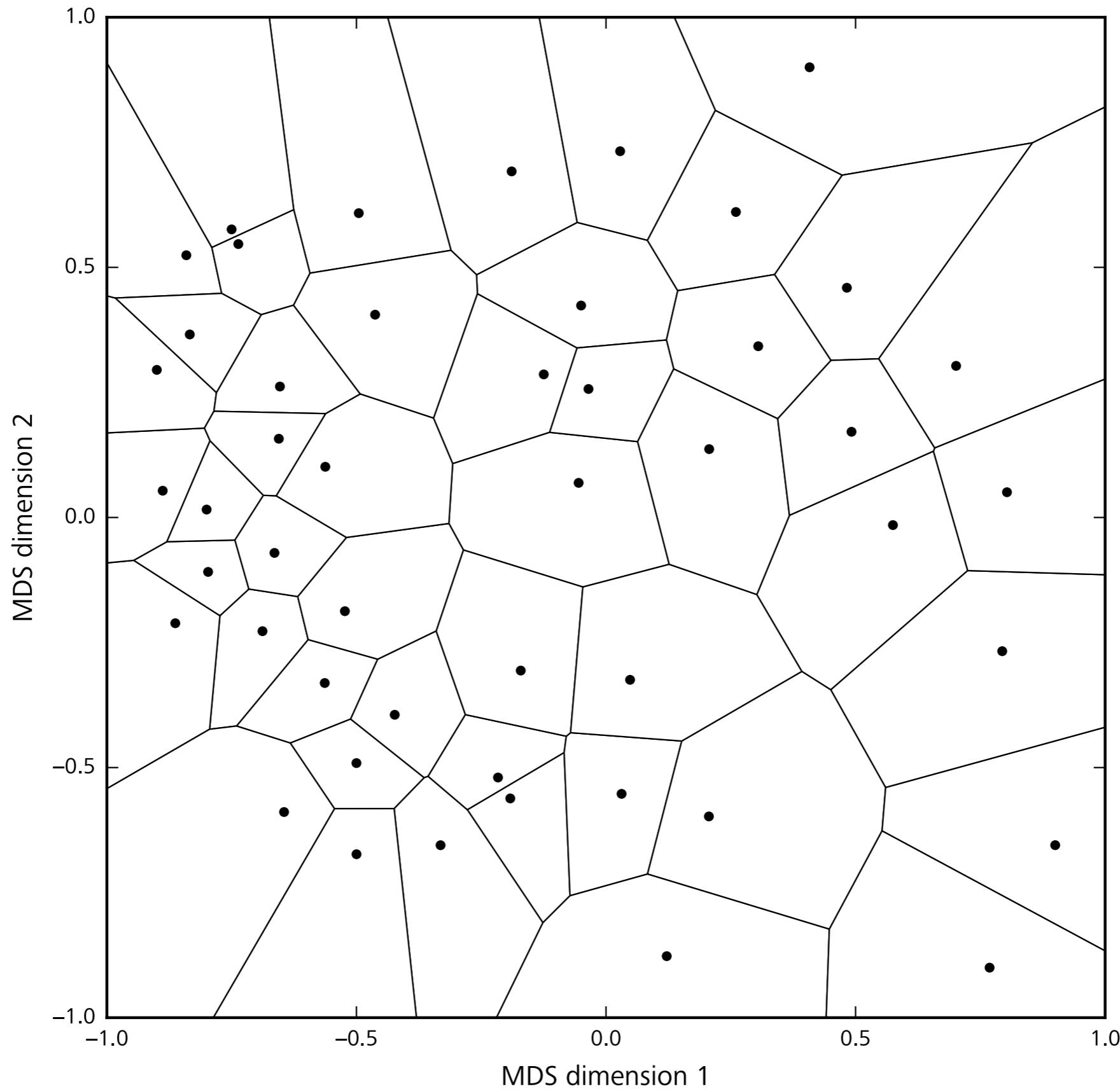


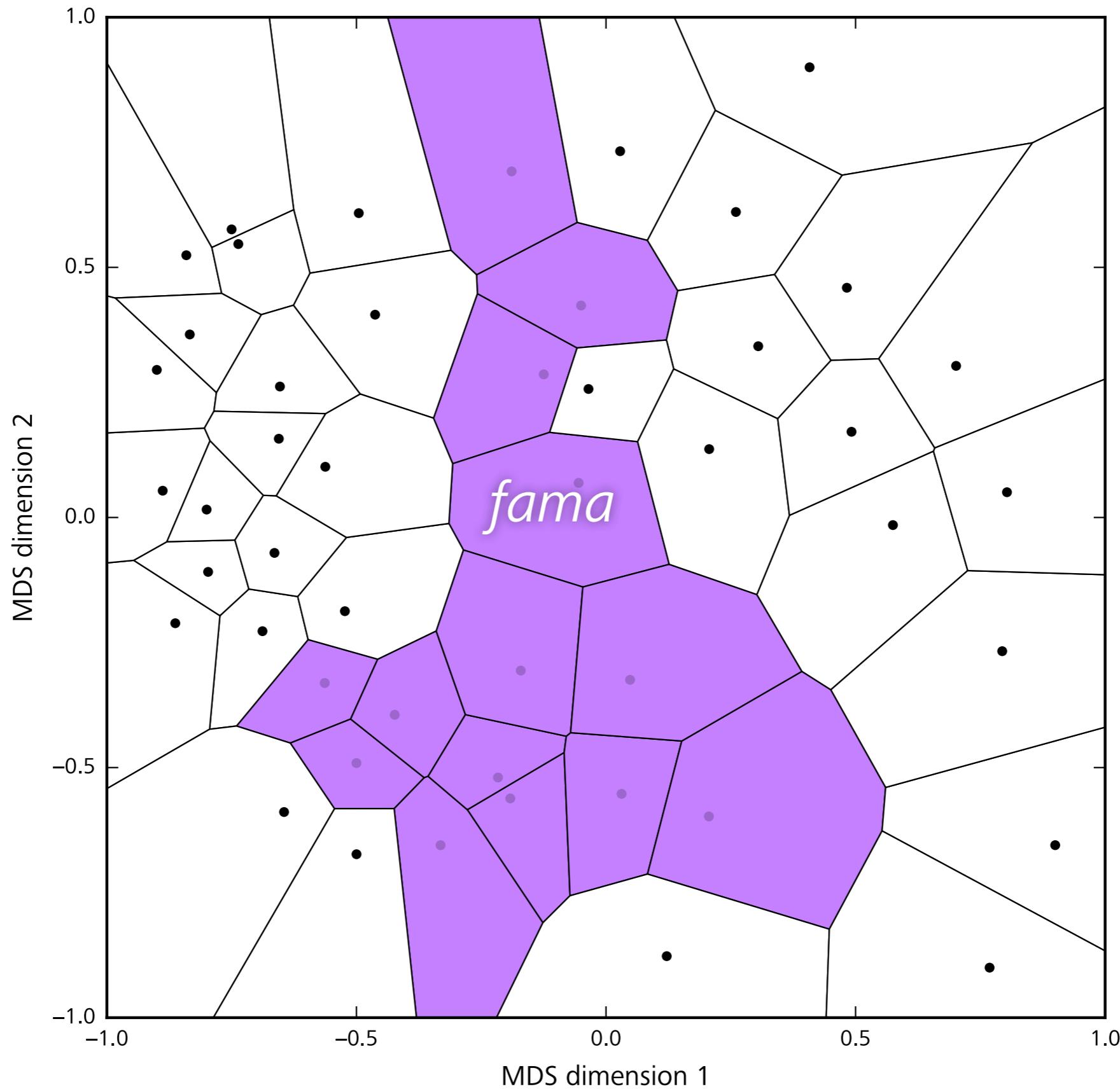
MDS dimension 2

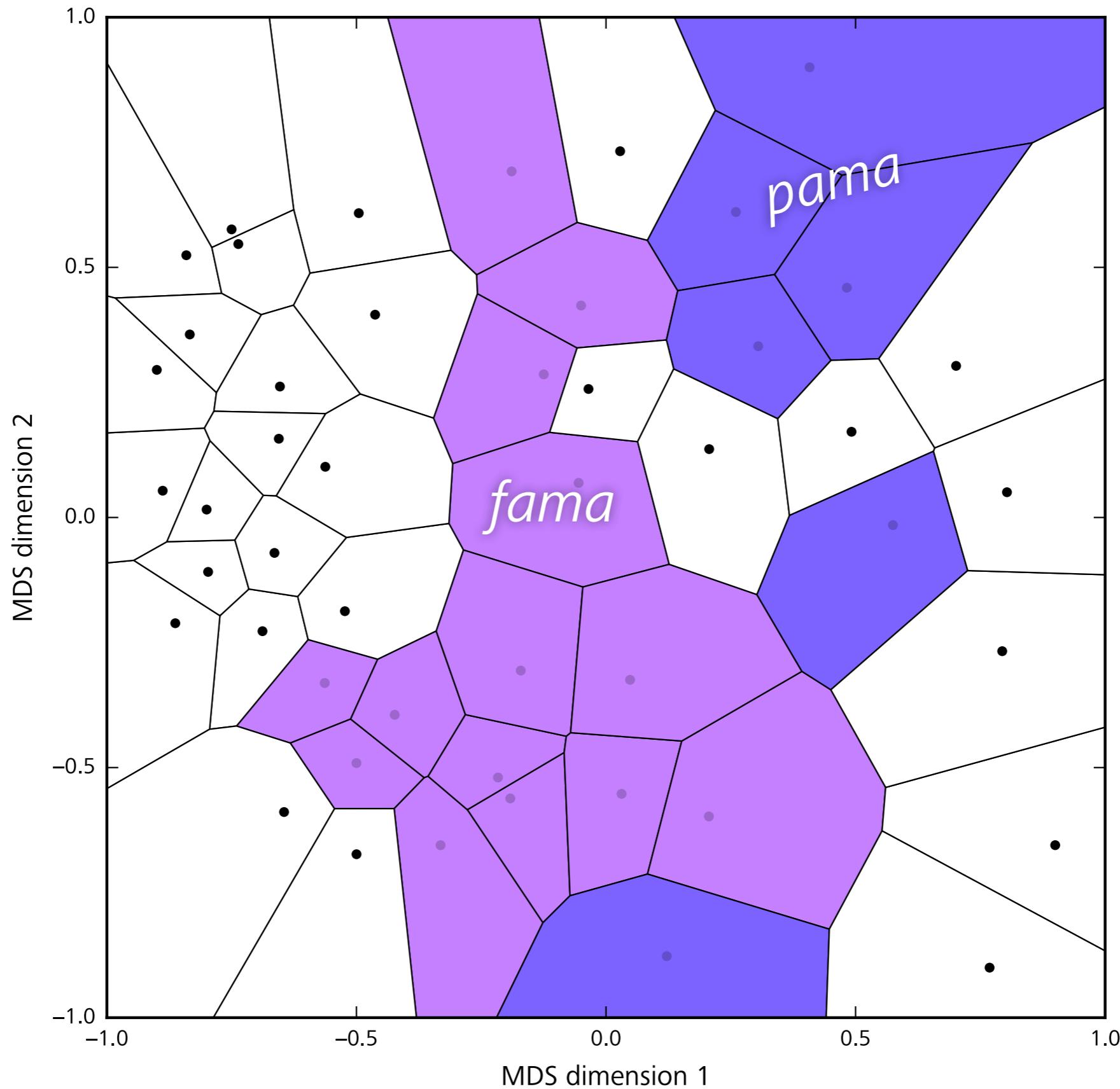
-1.0 -0.5 0.0 0.5 1.0

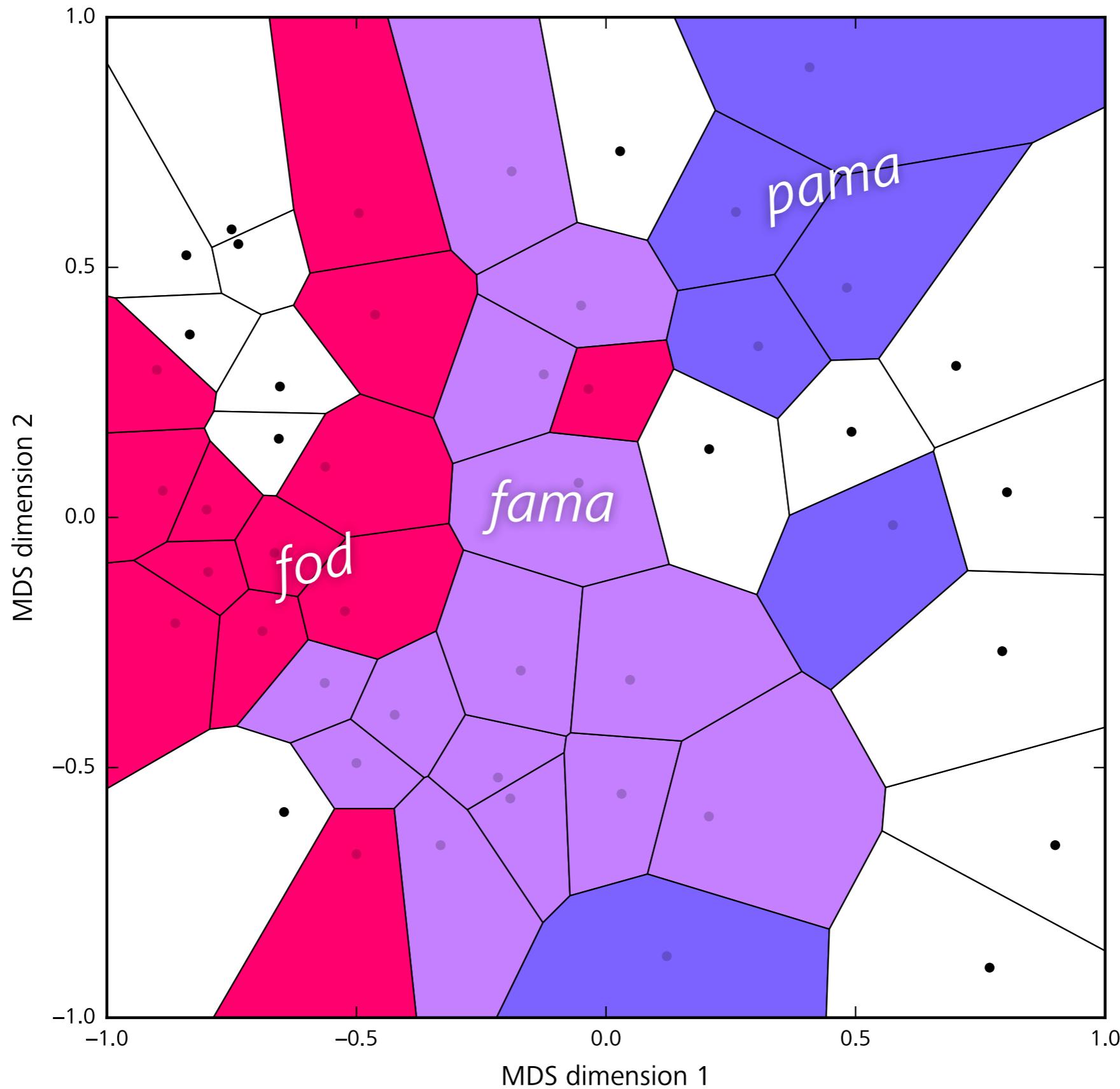
MDS dimension 1

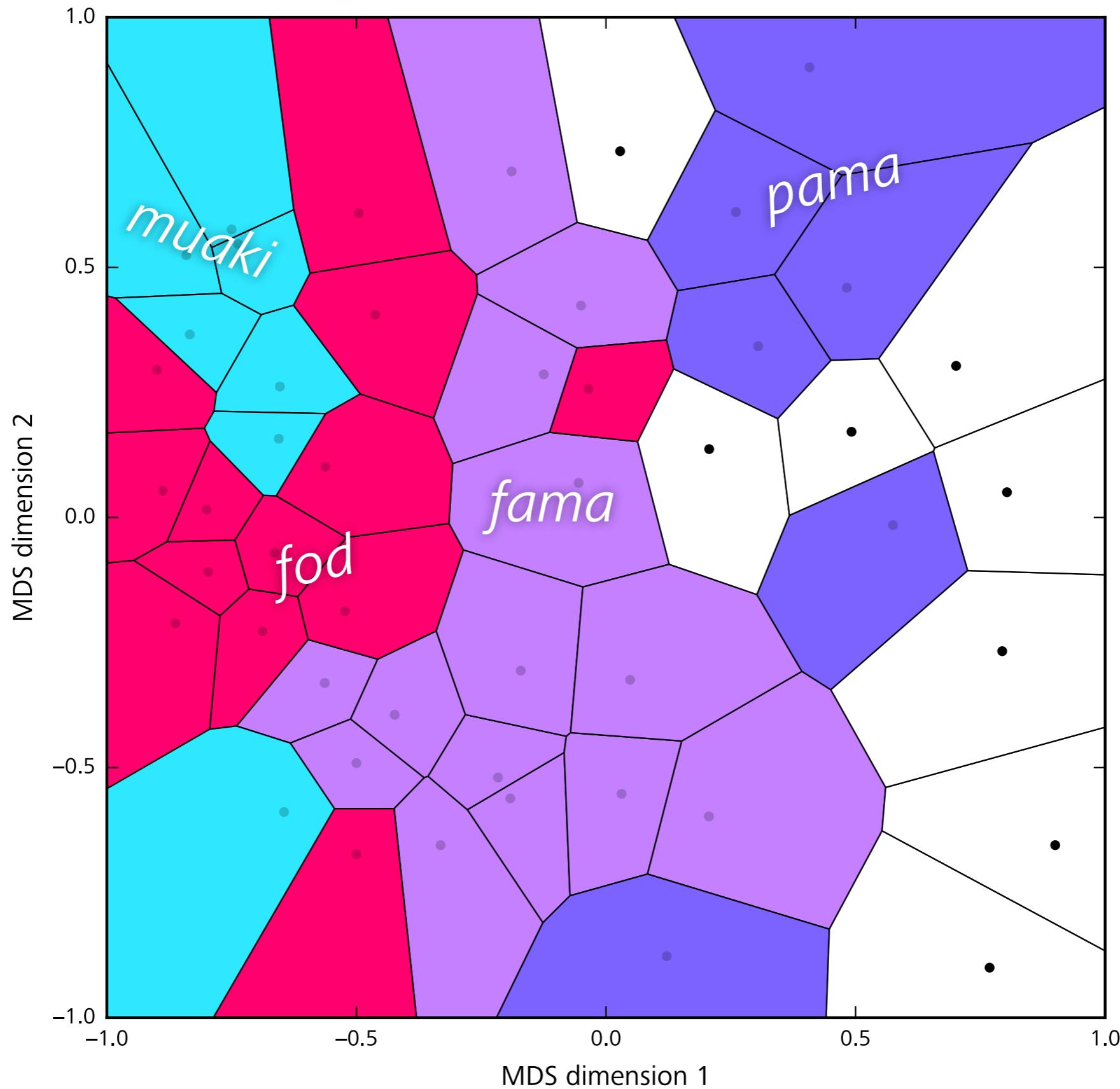


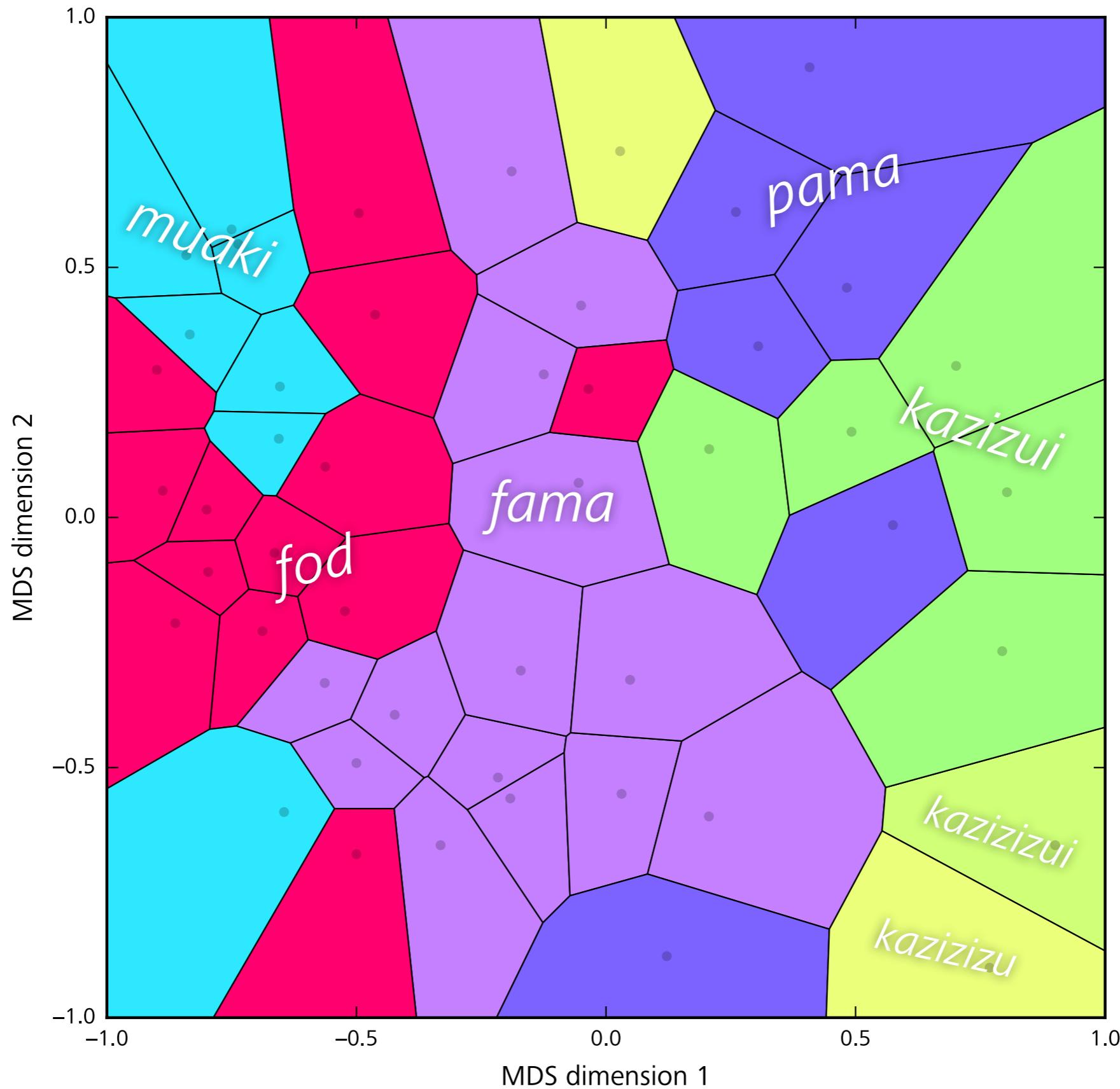


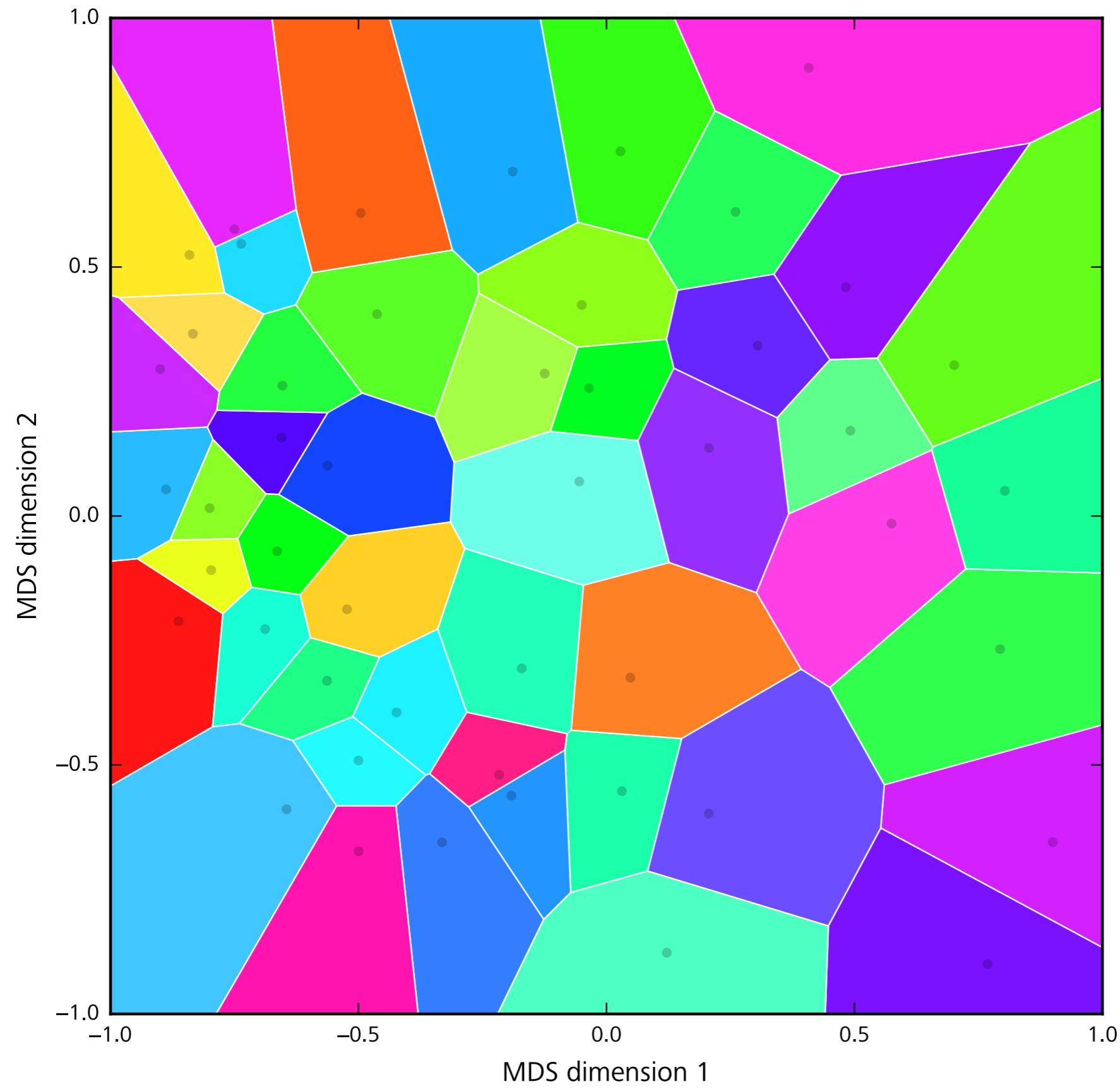




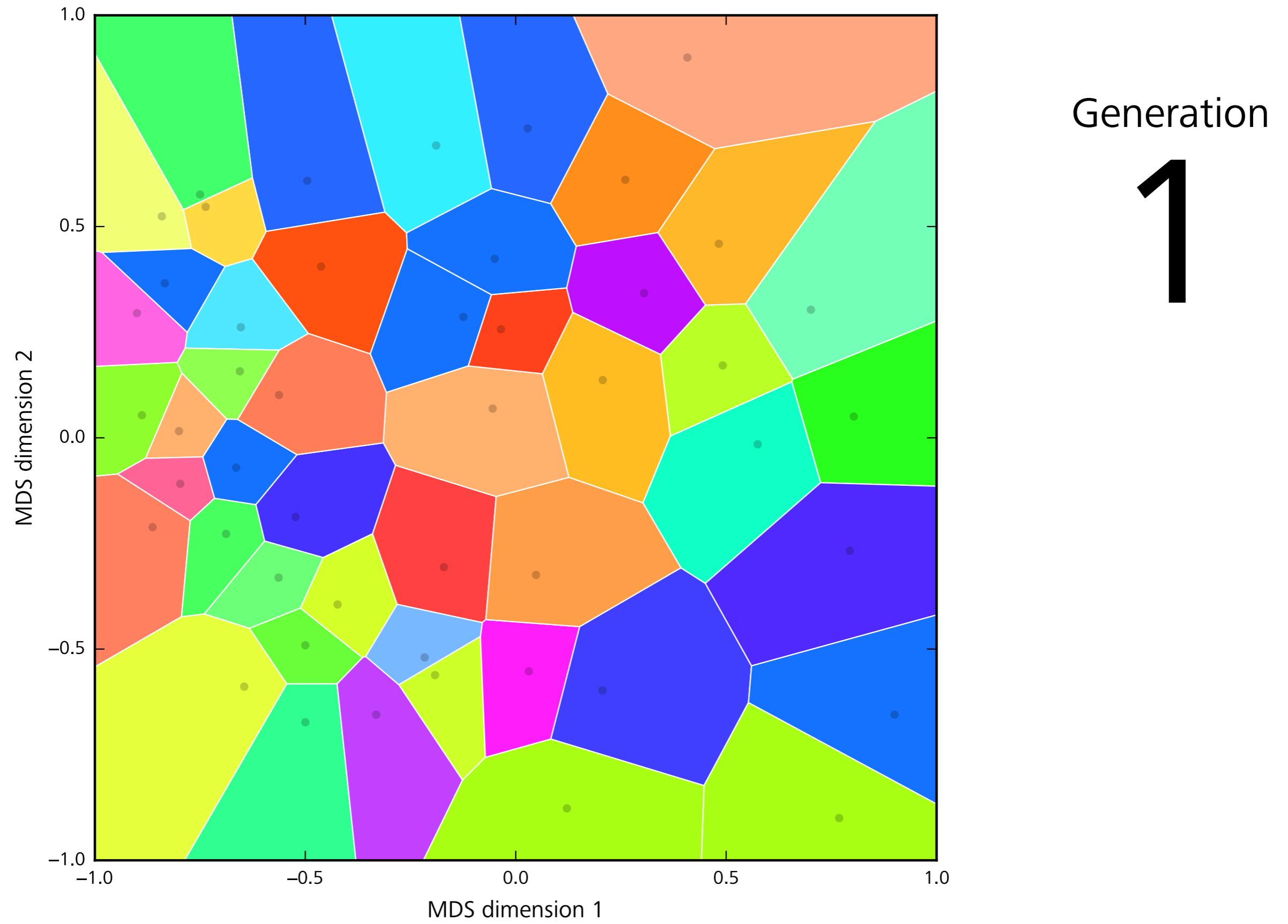


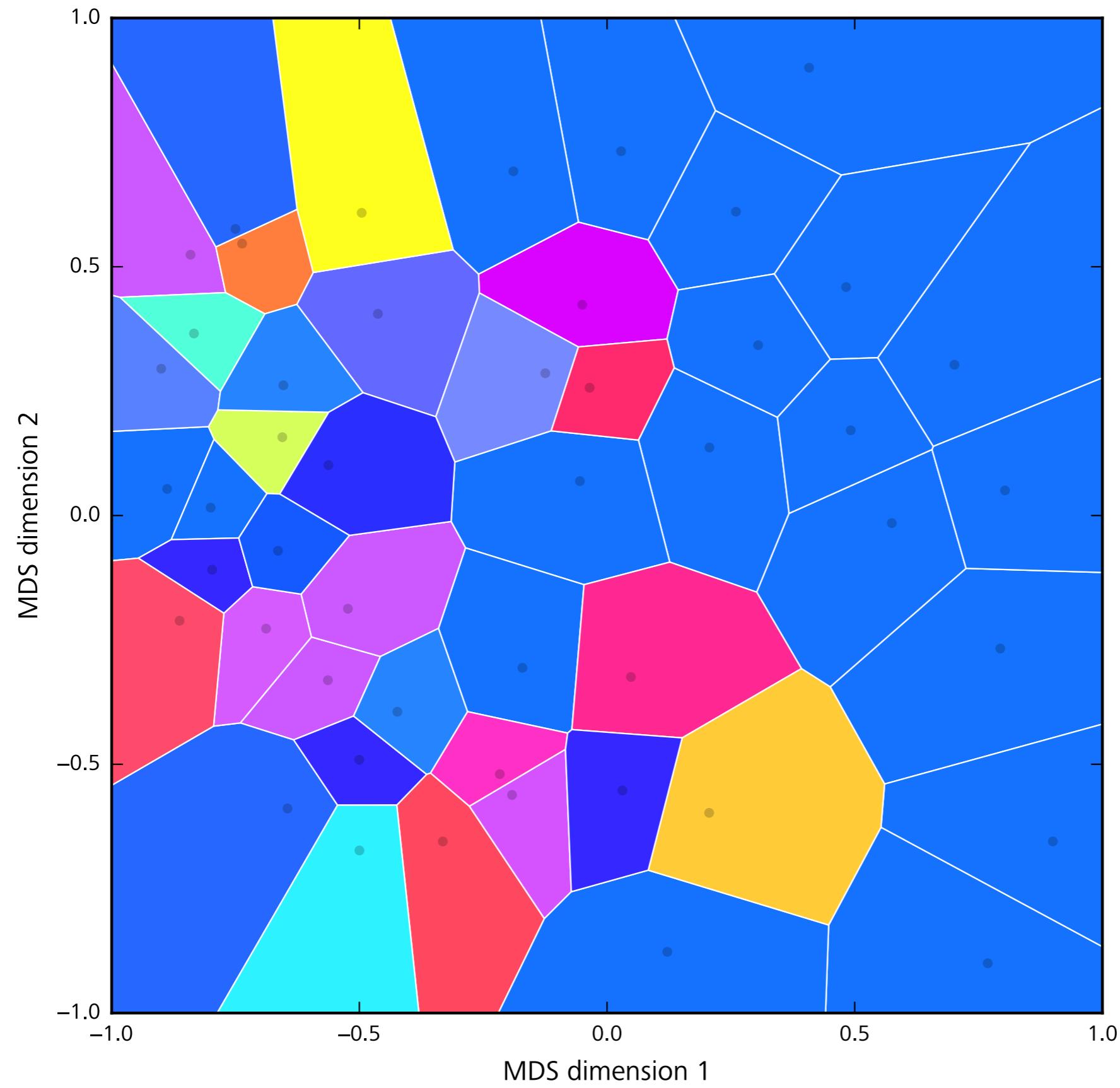




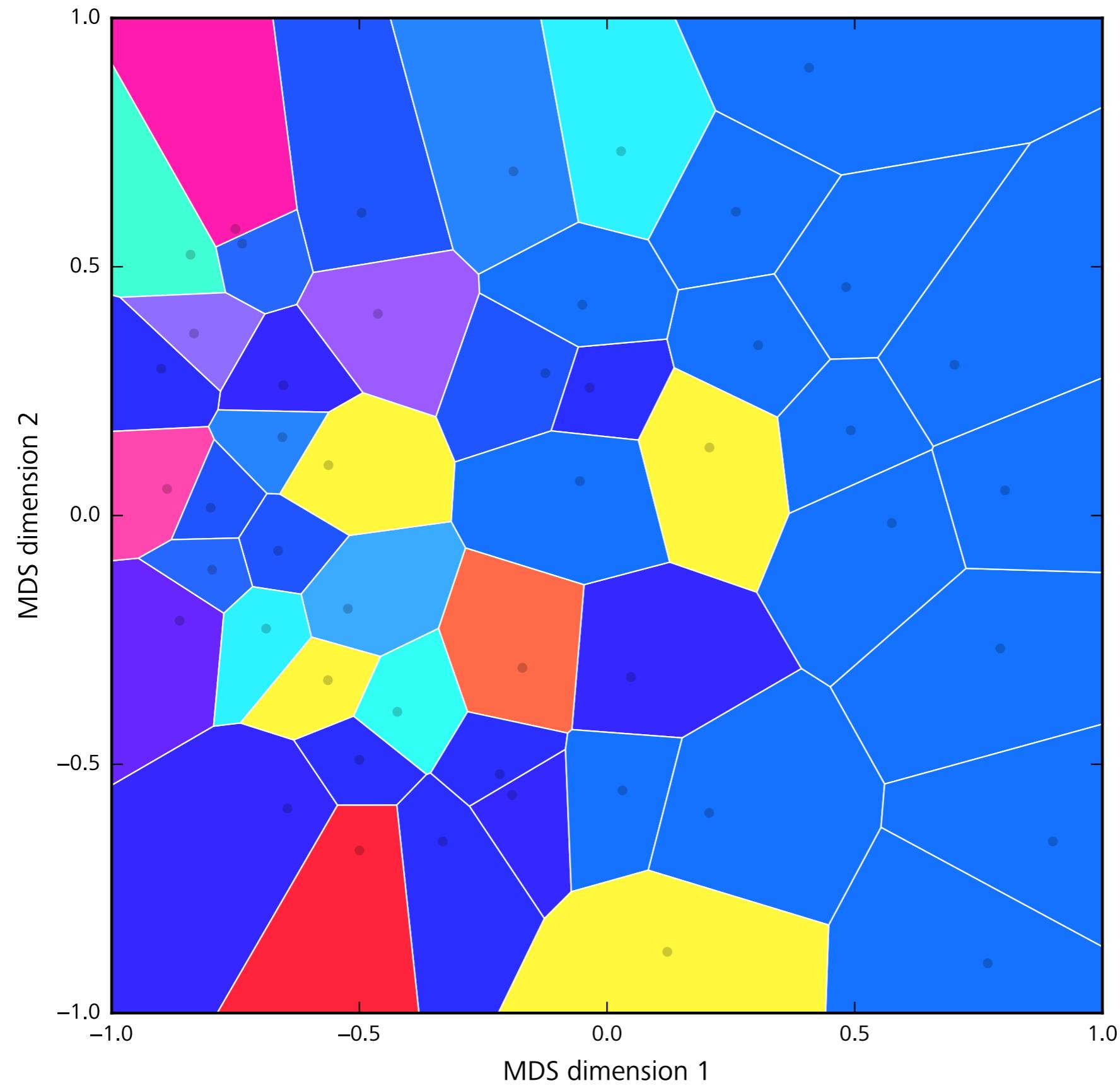


Generation
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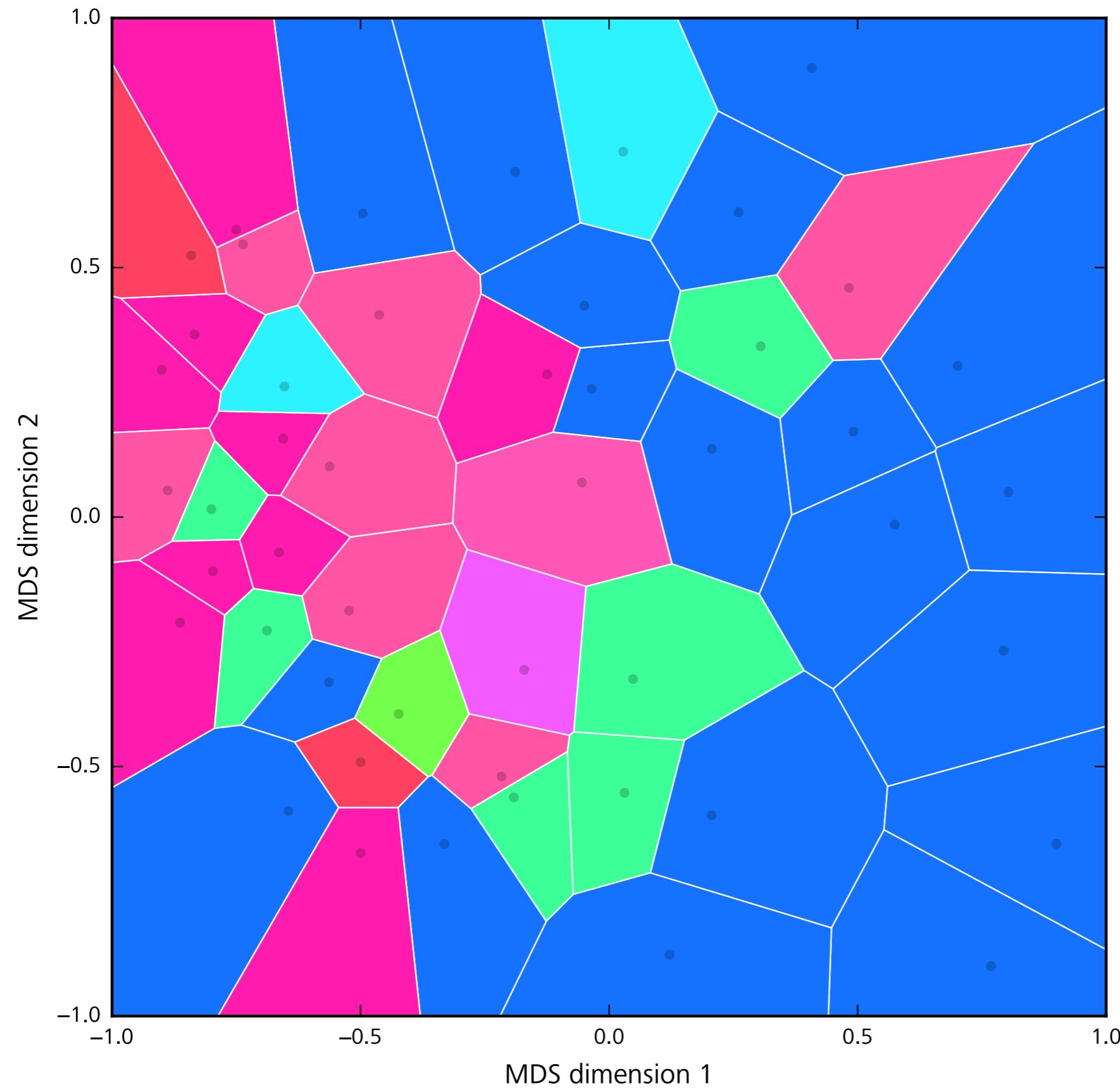




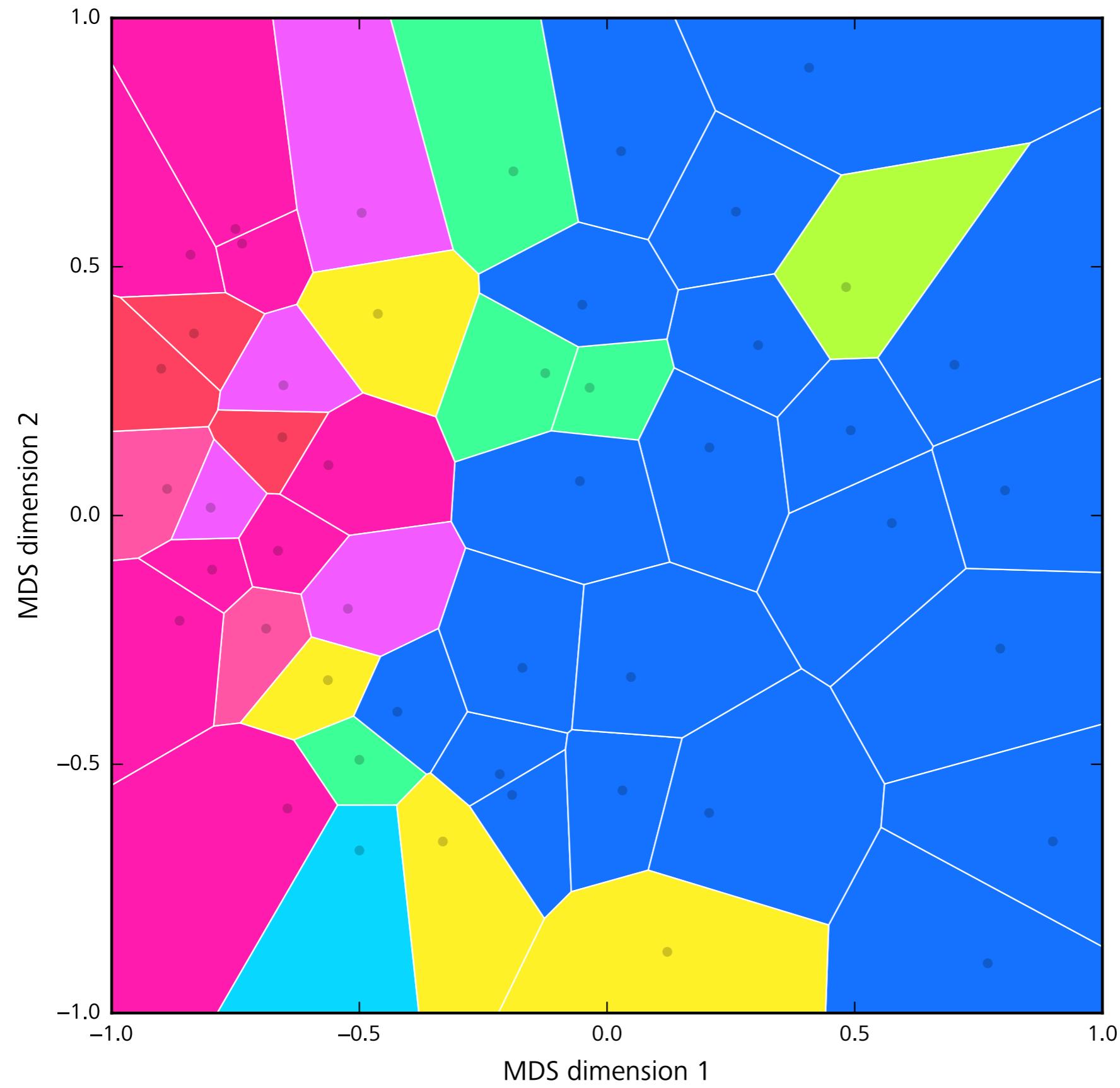
Generation
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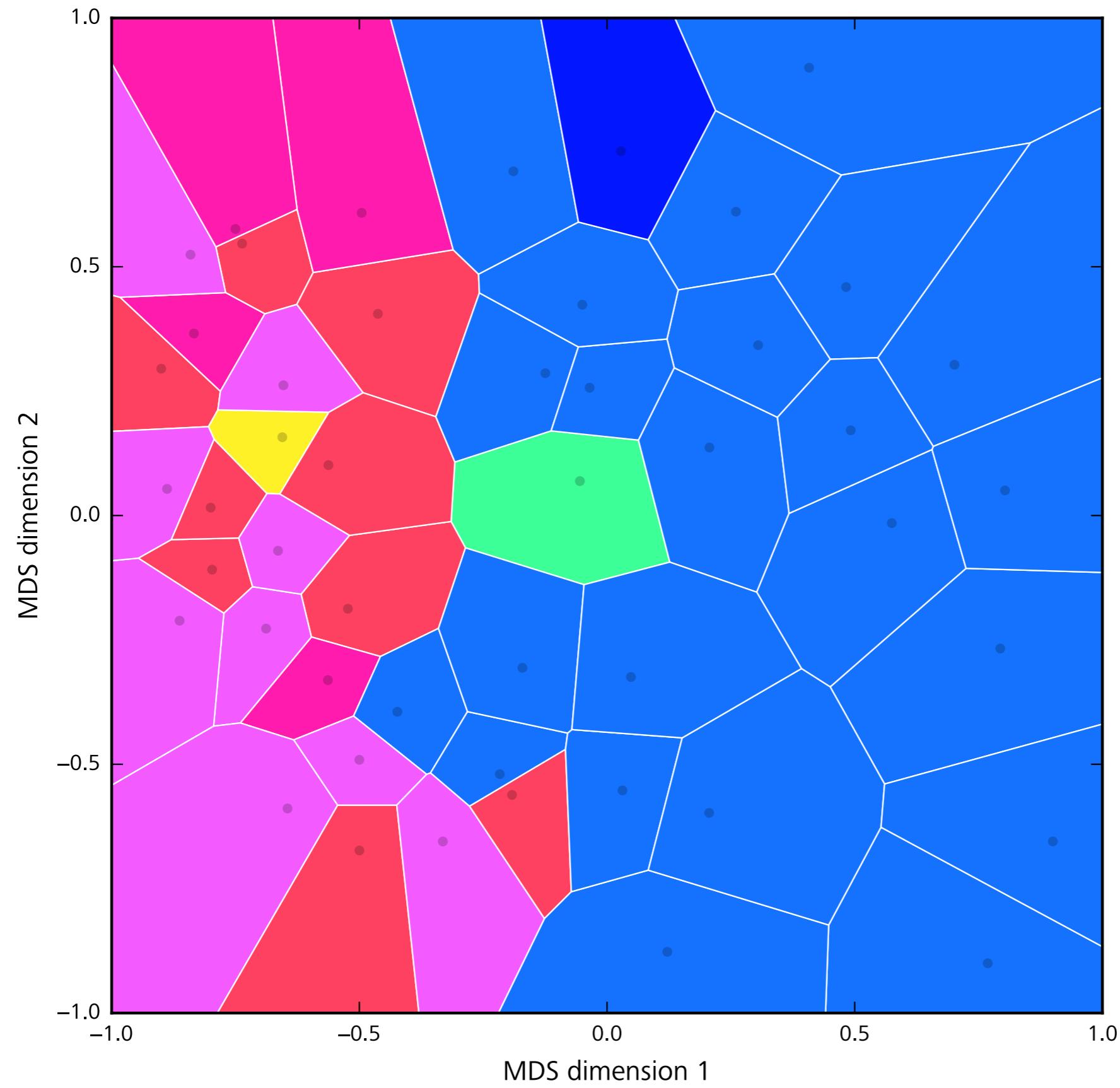
Generation
3



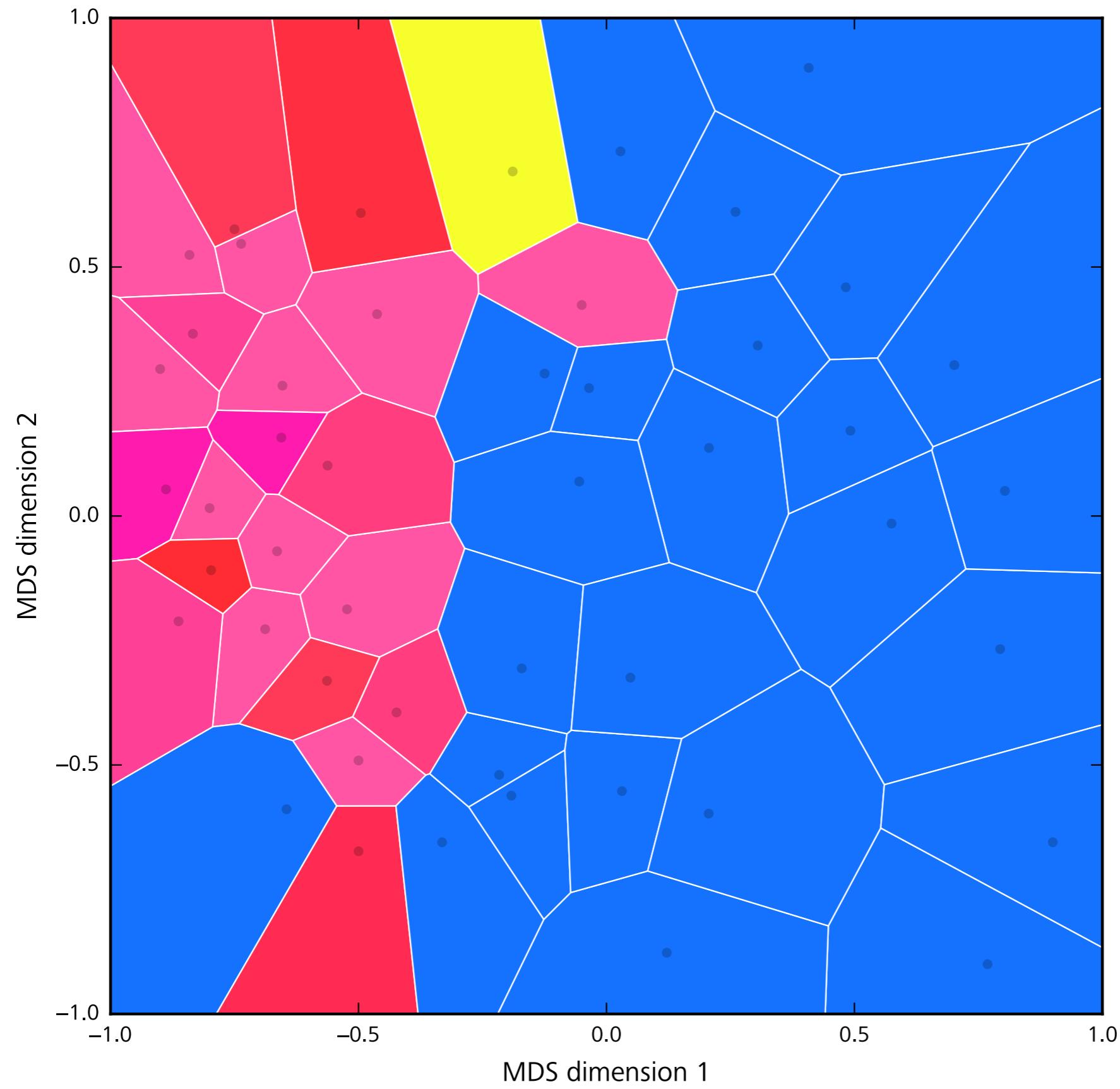
Generation
4



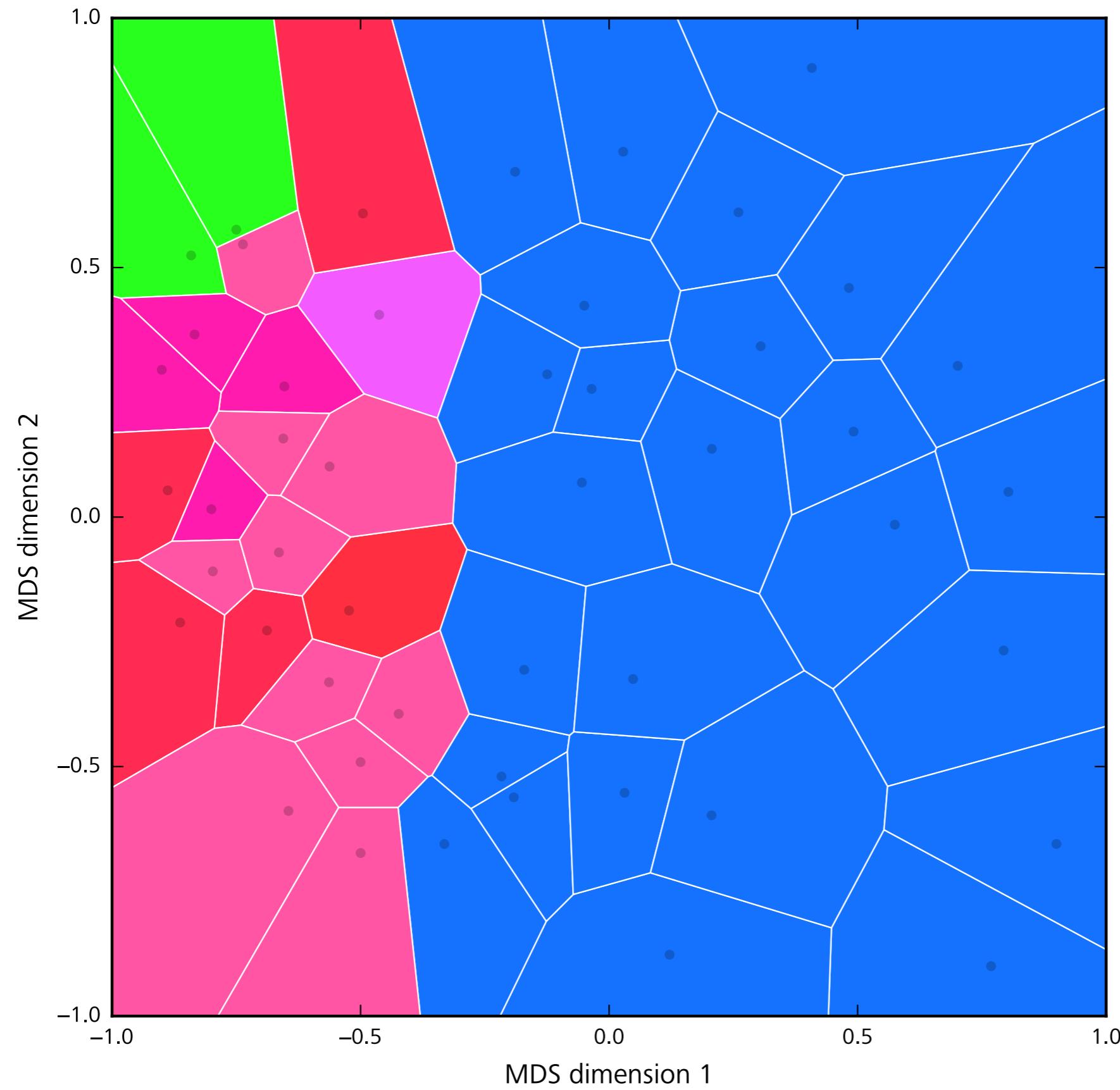
Generation
5



Generation
6

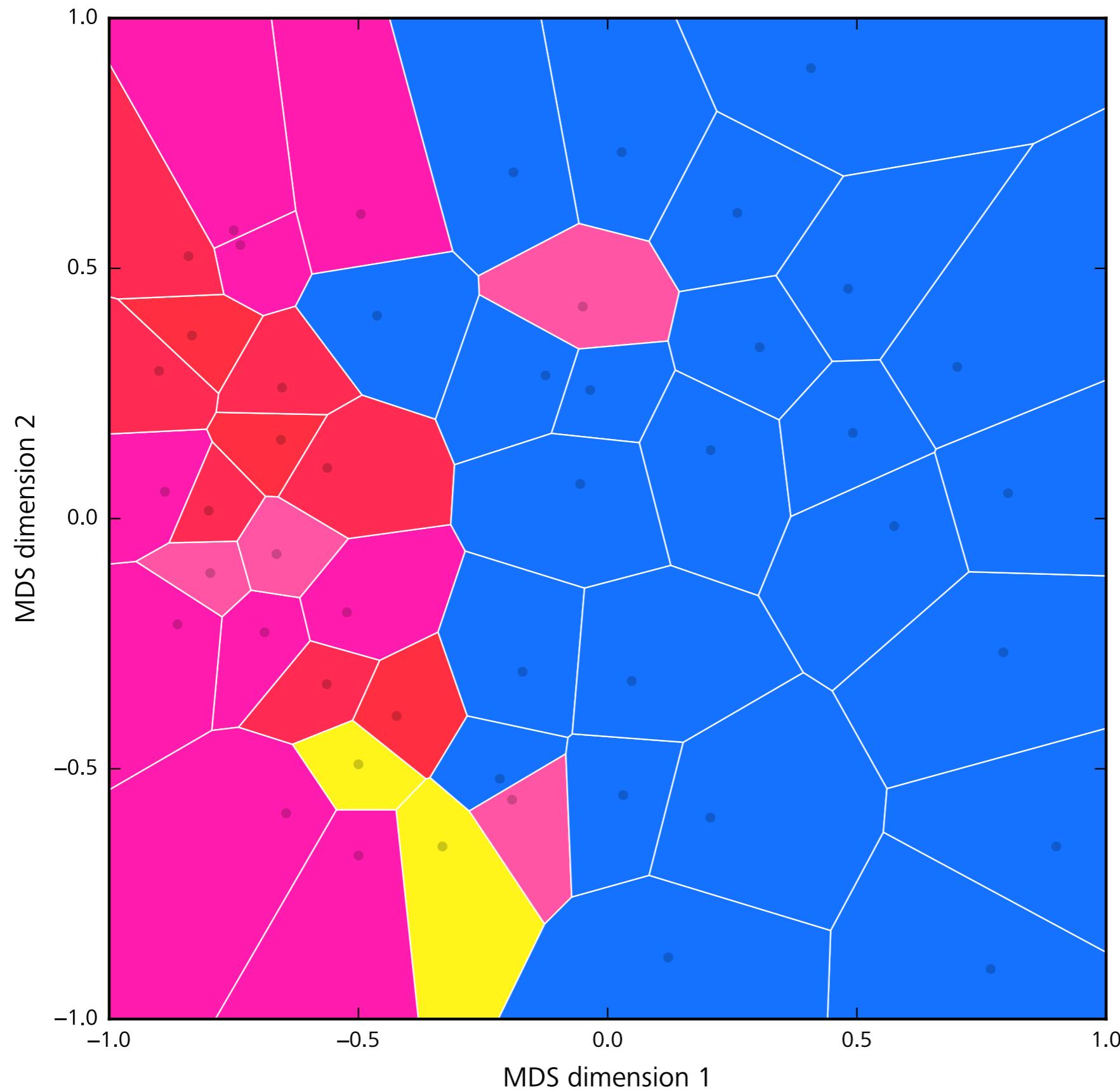


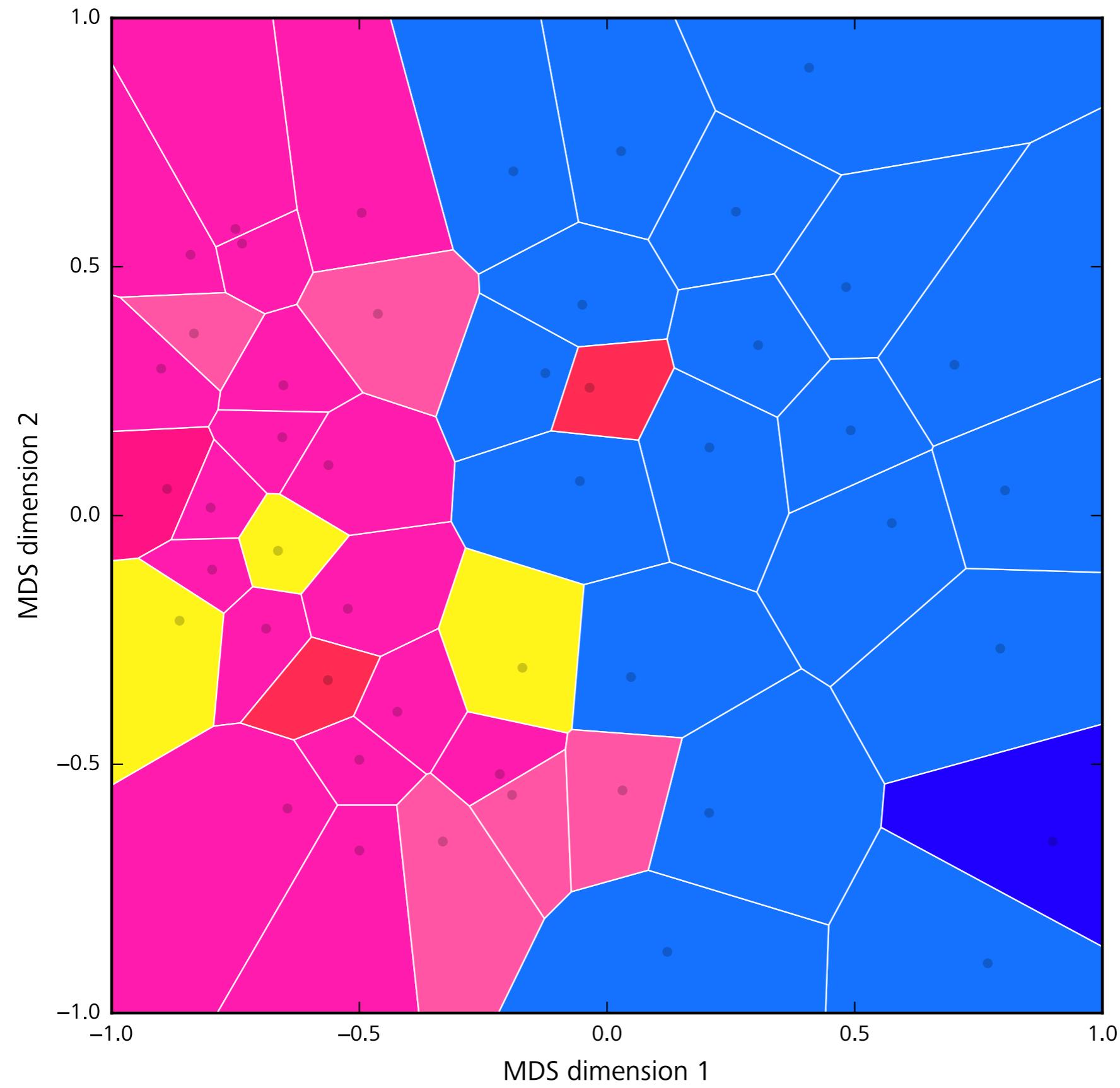
Generation
7



Generation
8

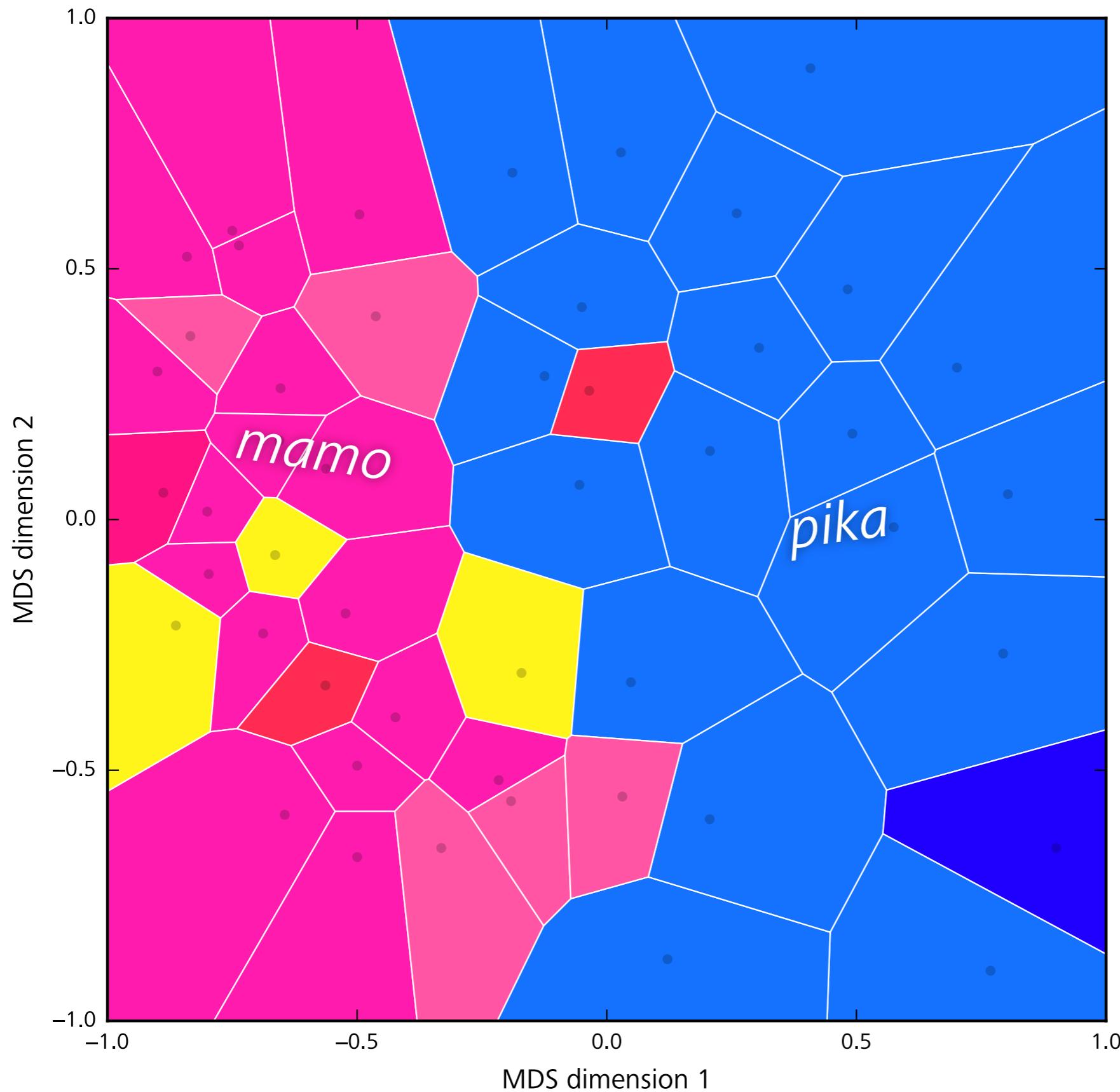
Generation
9





Generation
10

Generation
10



Conclusions

Experiment 1 showed that cultural evolution can deliver languages that categorize the meaning space under pressure from learnability.

This happens by losing categories and structuring the space in such a way that is easy to learn.

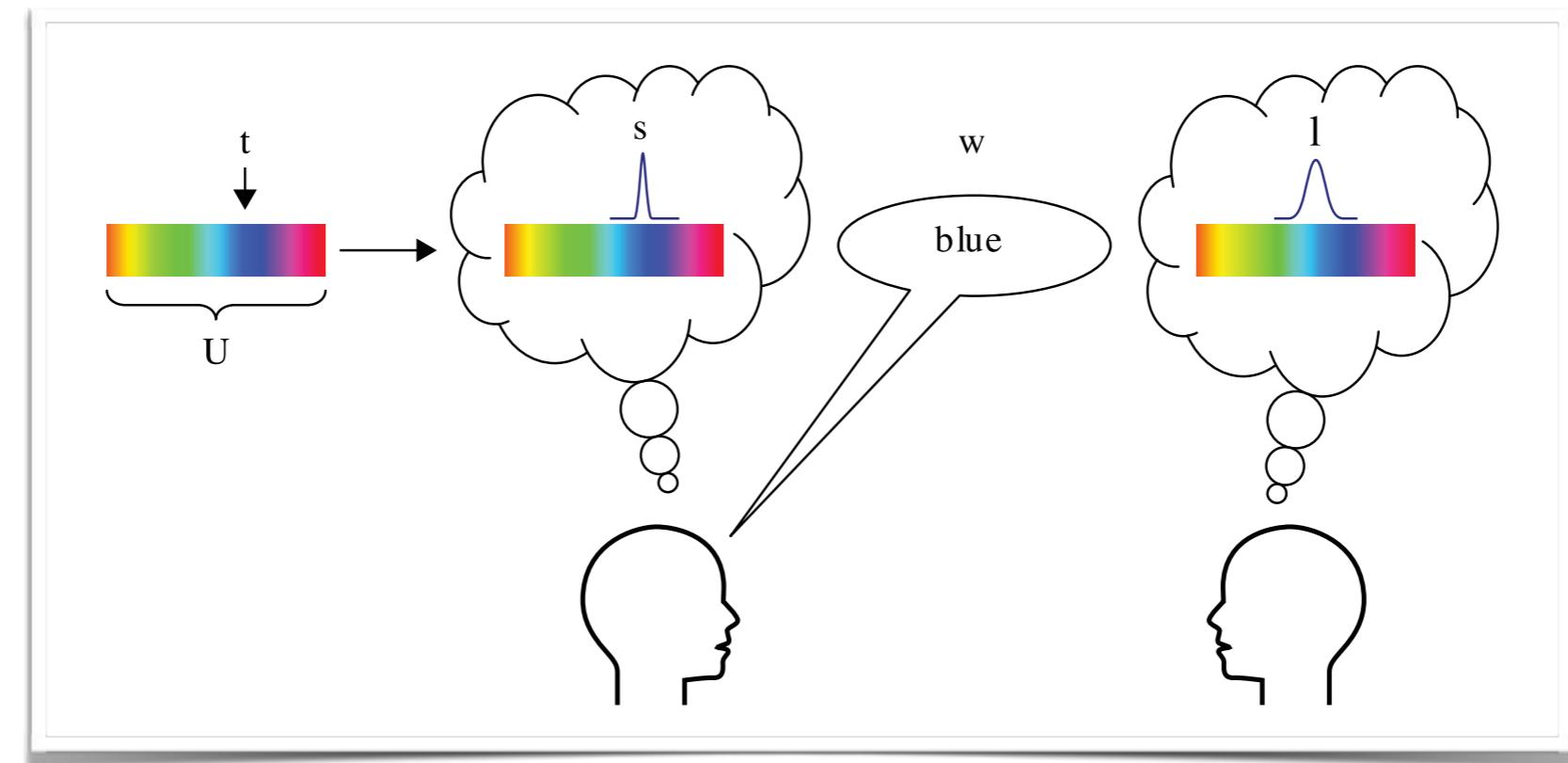
Experiment 2 combined a pressure for learnability **and** a pressure for expressivity derived from a genuine communicative task. This gave rise to languages that use both categorization and string-internal structure to be both learnable and expressive.

Ongoing work

Informativeness

Natural category systems “provide maximum information with the least cognitive effort” (Rosch, 1999).

Regier et al. formalize informativeness as “communicative cost”. The most informative category system is one that **minimizes** communicative cost.



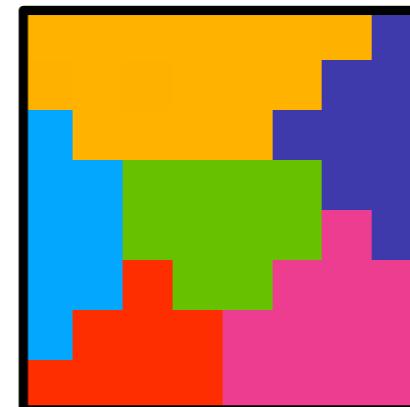
Informativeness

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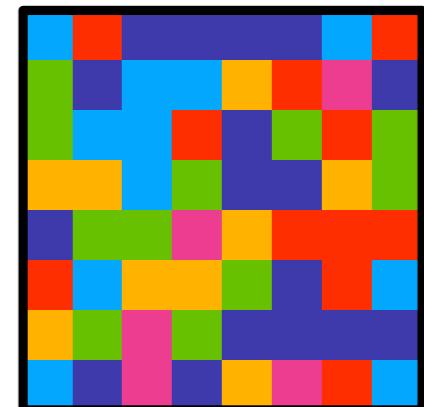
Regier et al. formalize informativeness as “communicative cost”. The most informative category system is one that **minimizes** communicative cost.

Negative logarithm of average within-category similarity, summed for all possible targets.

$$\sum_{t \in T} -\log_2 \left(\frac{1}{|C_t|} \sum_{c \in C_t} e^{-s \cdot d_{t,c}^2} \right)$$

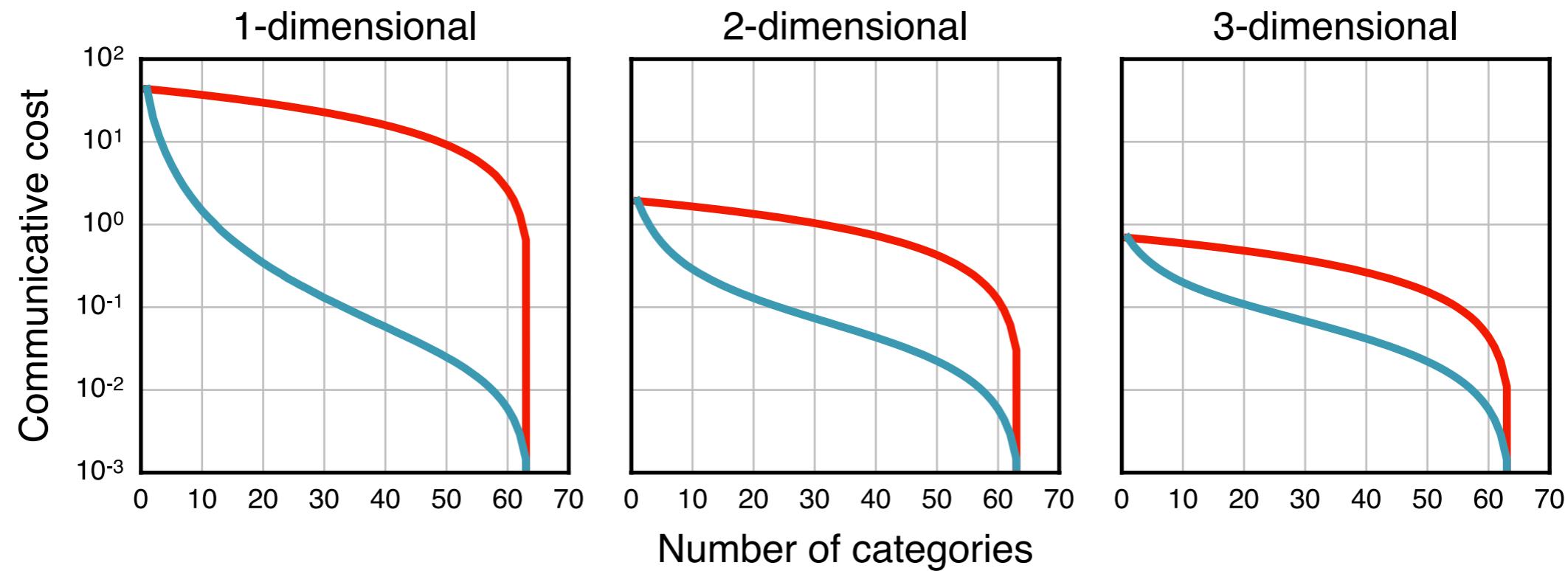
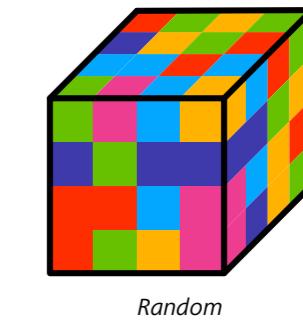
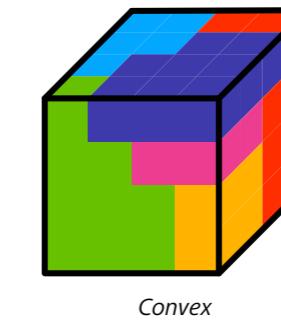
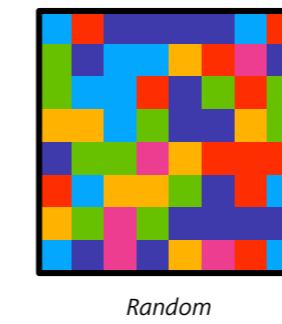
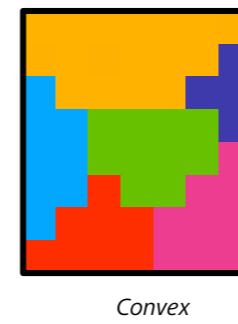
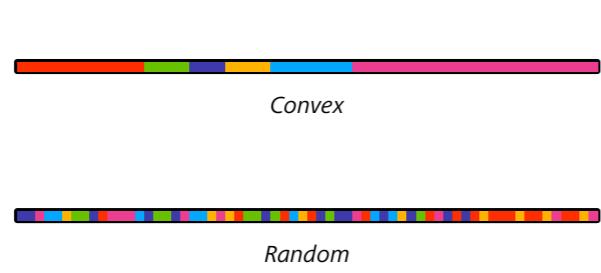


Convex



Random

Informativeness

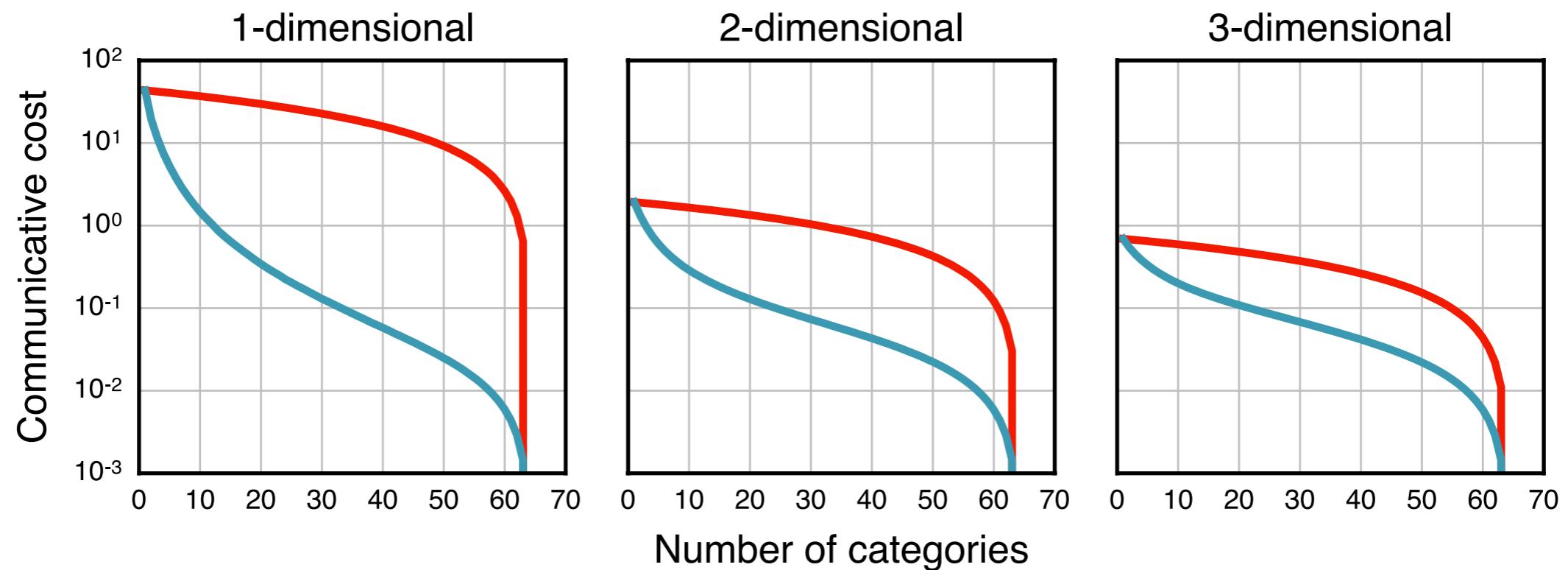


Three predictions

Maximize number of categories The use of a single category has the highest cost and is therefore the least informative system; placing every item in its own category reduces the cost to 0 (maximum informativeness).

Maximize dimensionality Representing 64 items using three dimensions is more informative than representing 64 items using one dimension (for a given number of categories).

Maximize convexity A convex category system is always better than or equal to a non-convex system in terms of minimizing communicative cost. Convex category structures are optimal.



Except: The learnability tradeoff

Maximize number of categories But: Learning an infinite number of categories is not possible given finite time and cognitive resources.

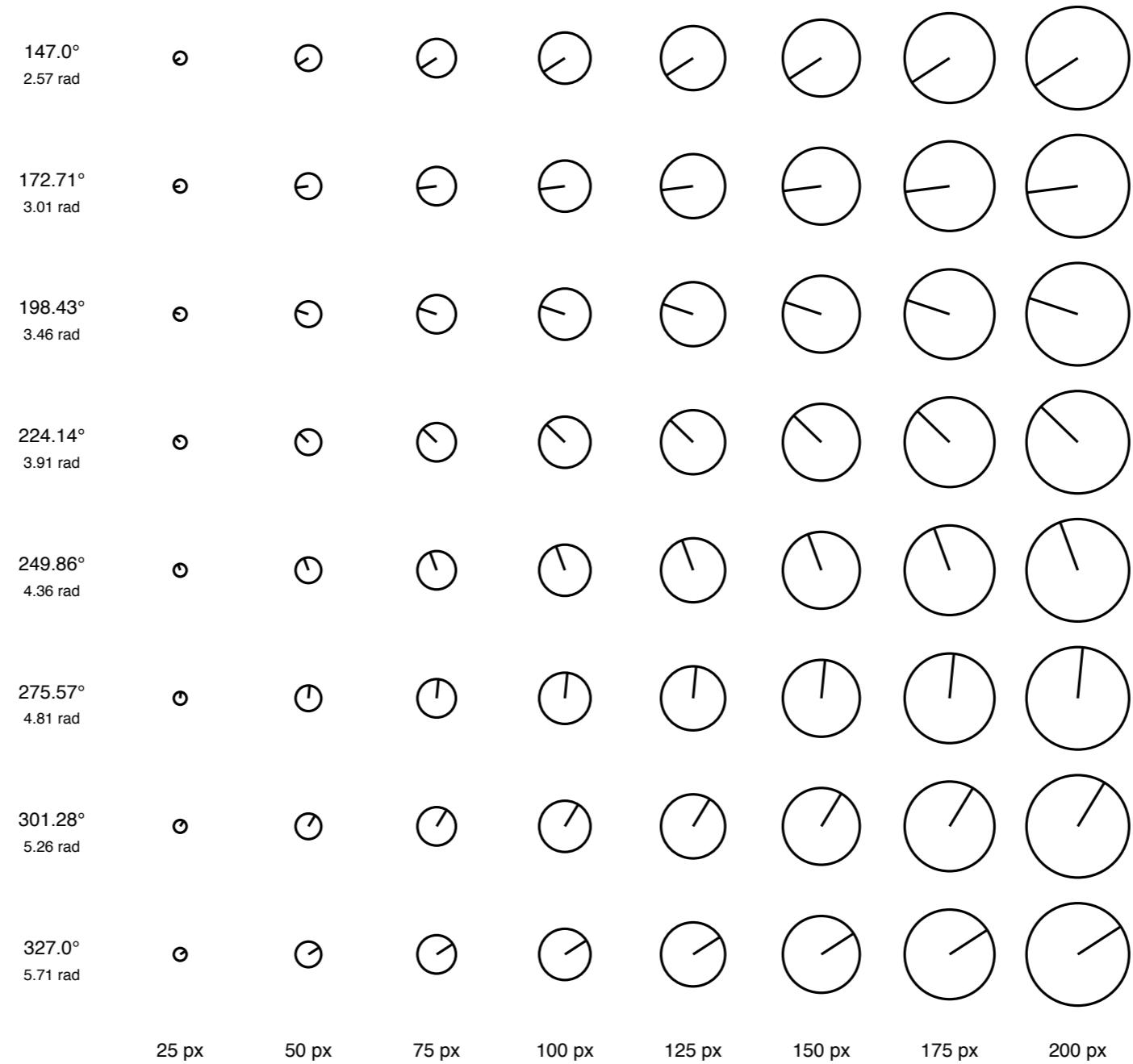
Maximize dimensionality But: Representing categories using infinite feature dimensions would be impossible to process.

However:

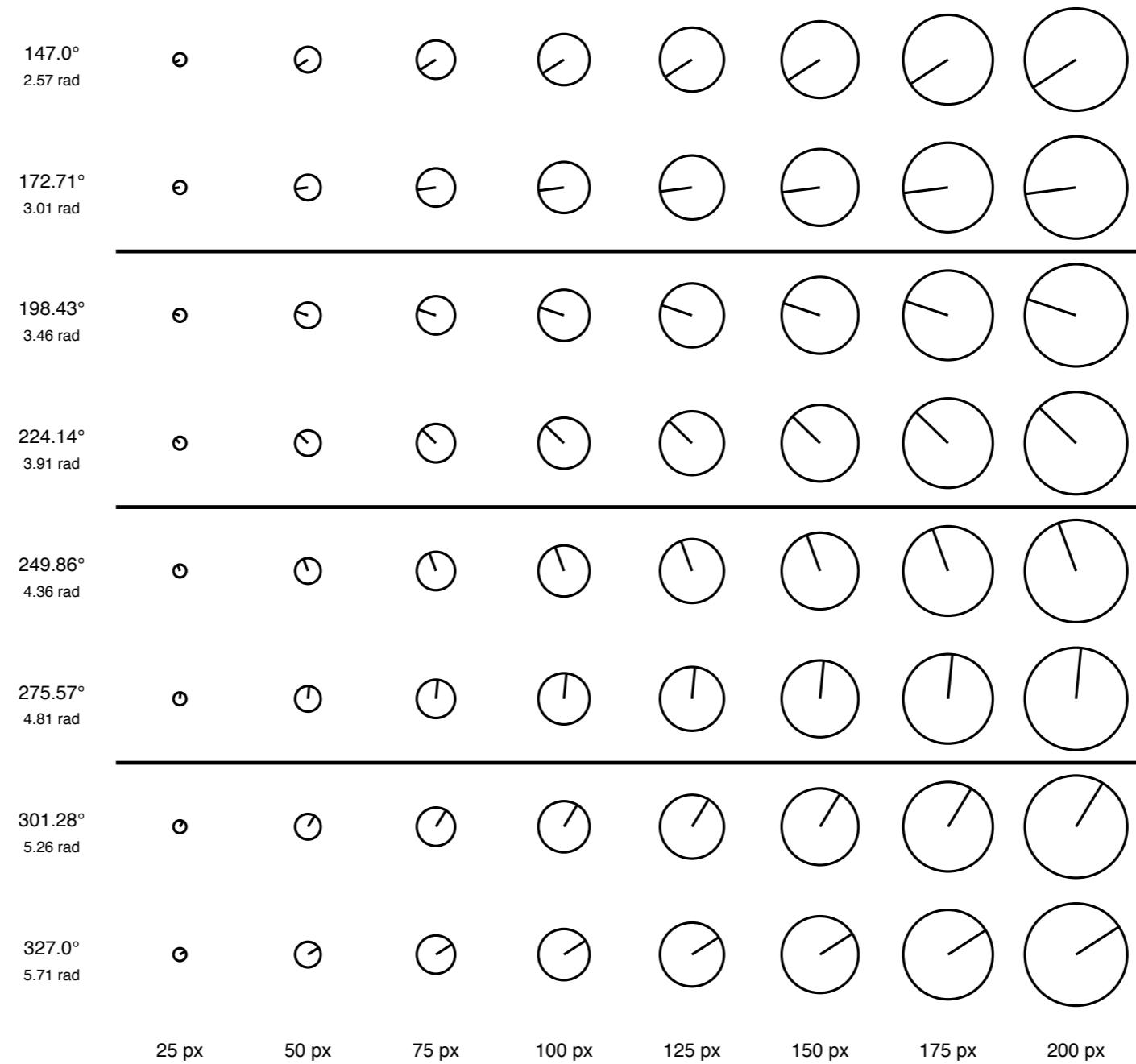
Maximize convexity Convexity leads to systems that are both more informative and potentially easier to learn.

Thus, the property of convexity seems to be particularly interesting (Gärdenfors, 2000, 2014).

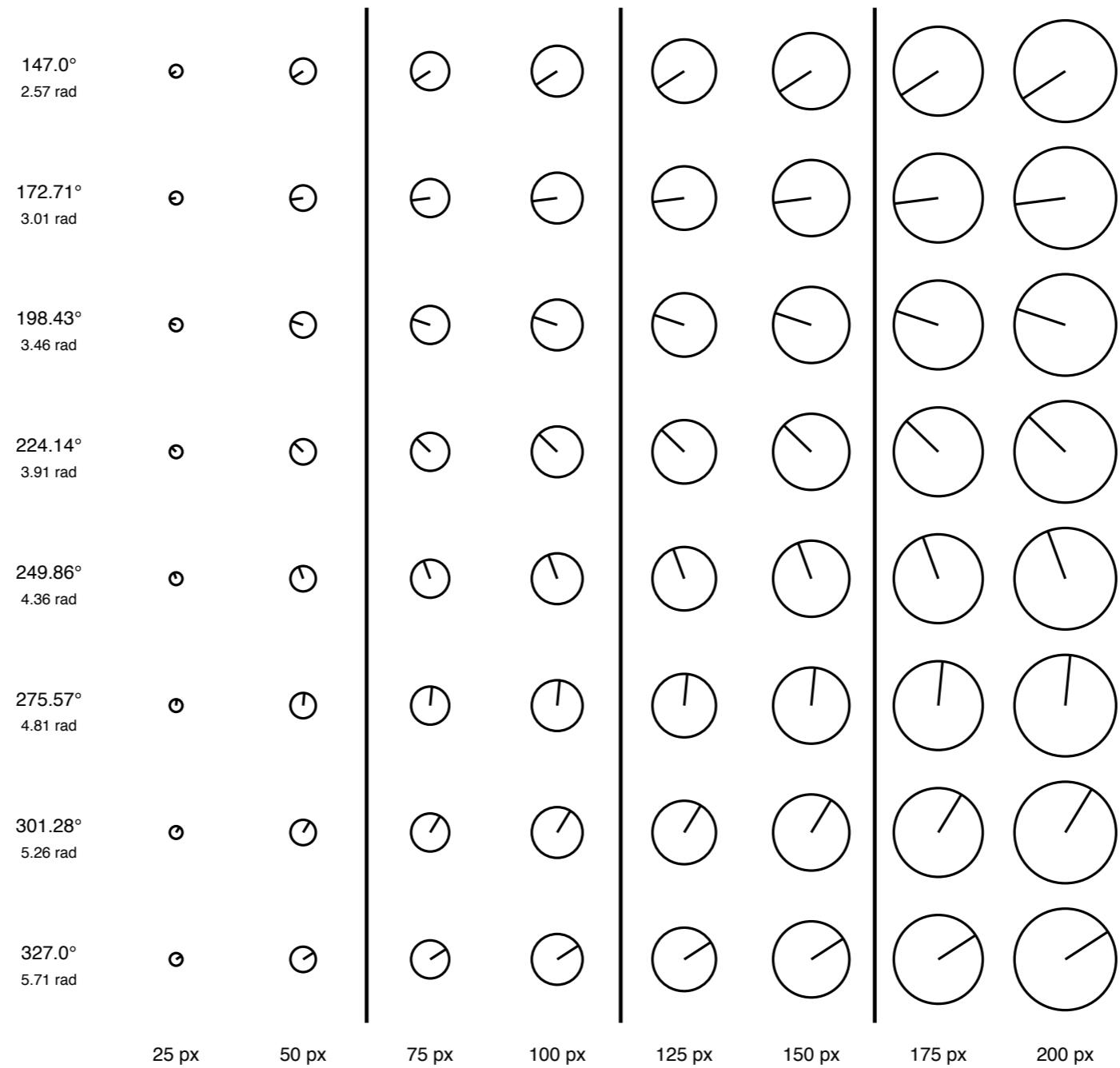
Stims: Shepard circles



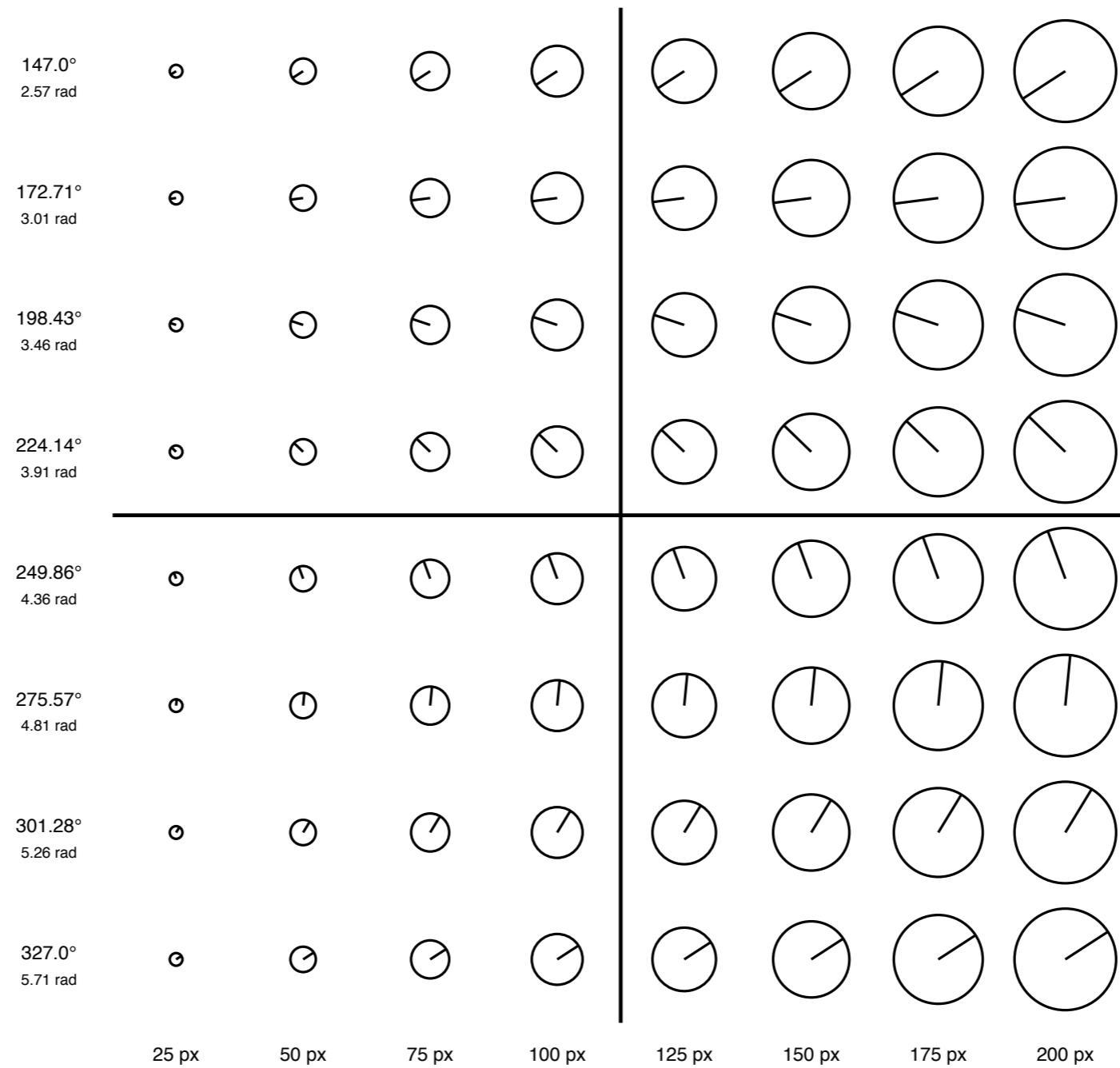
Stims: Shepard circles



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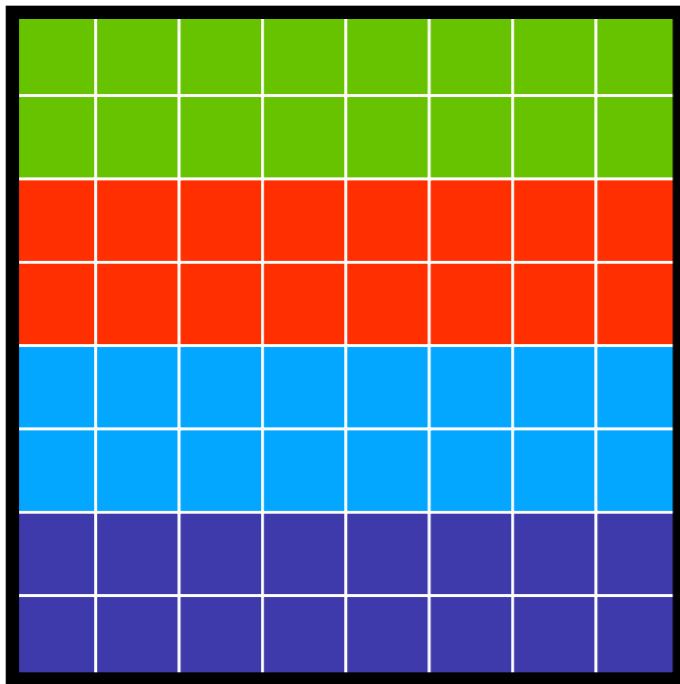


Stims: Shepard circles

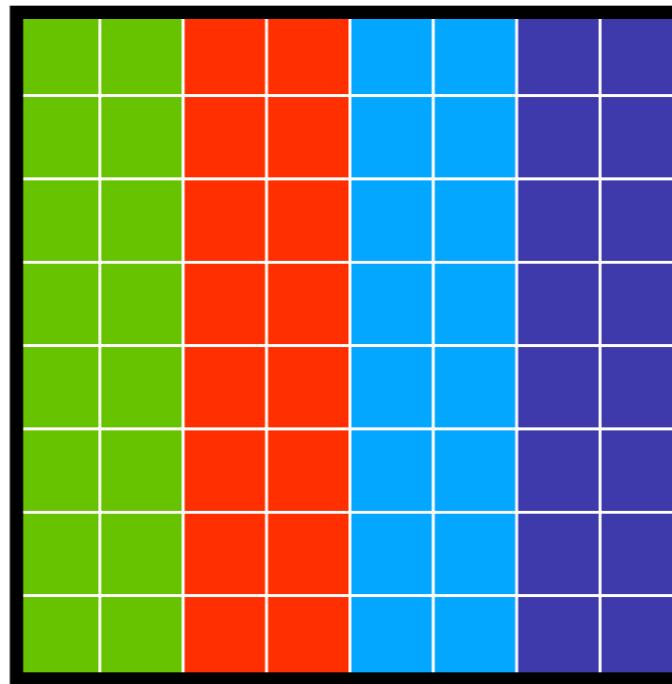


Squares and Stripes: Three category systems

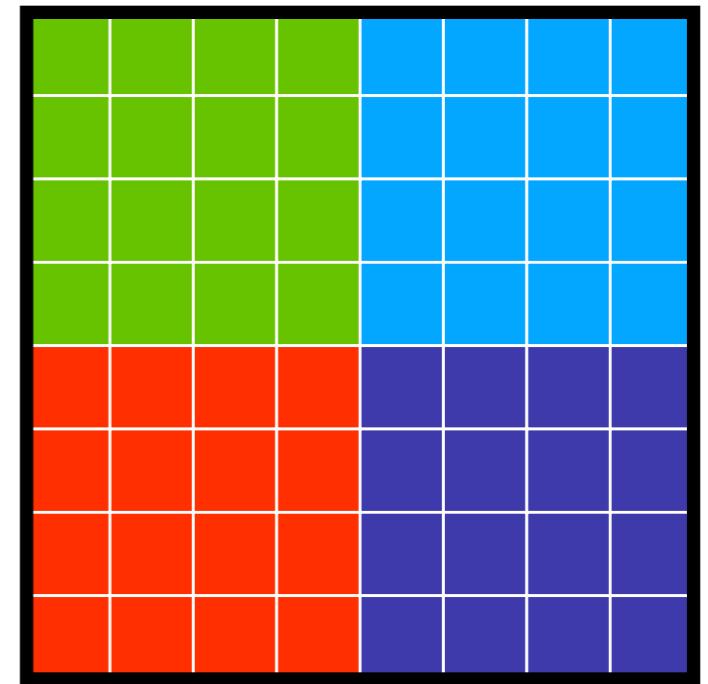
Angle-only



Size-only



Angle & Size

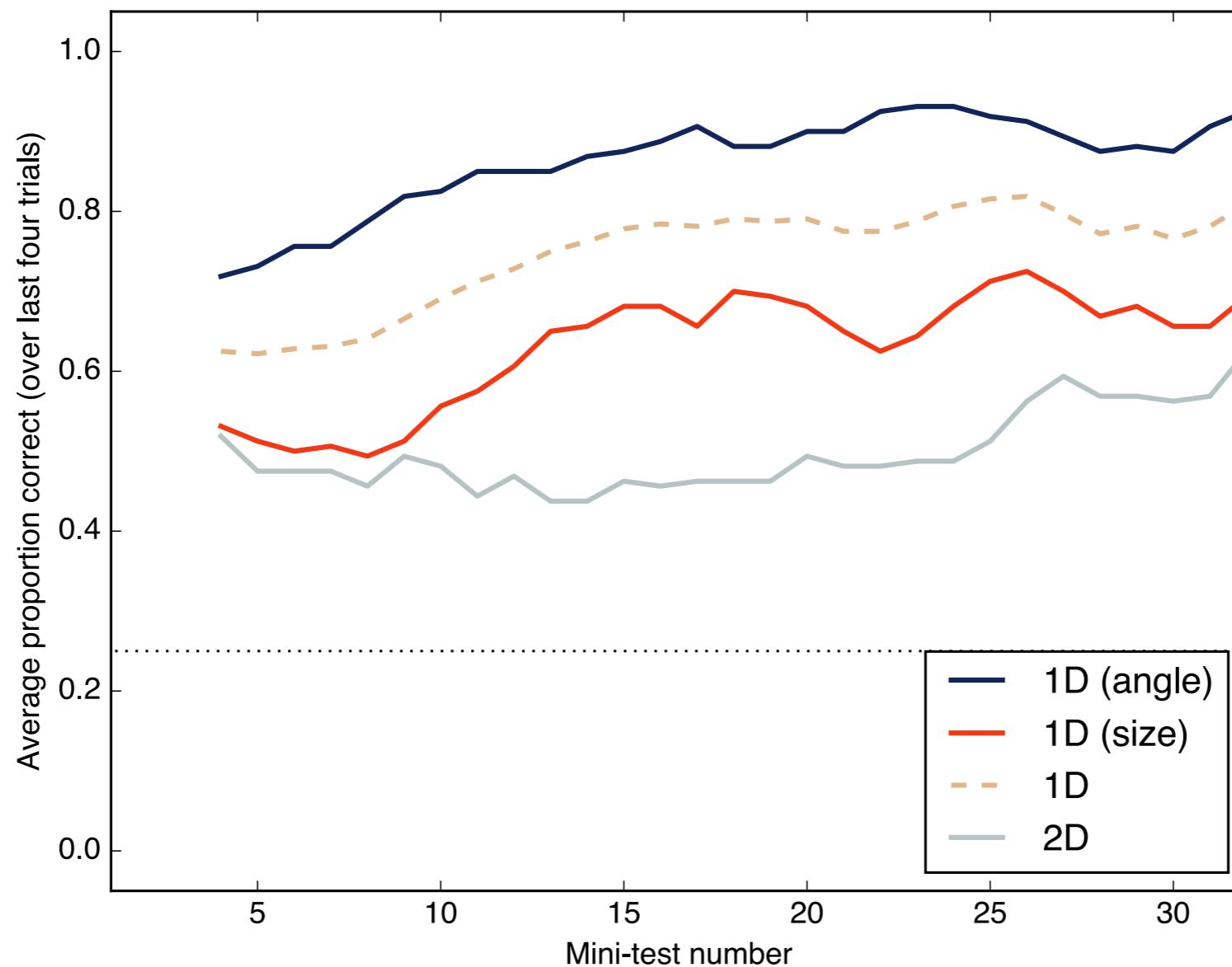


Easy to learn but low informativeness

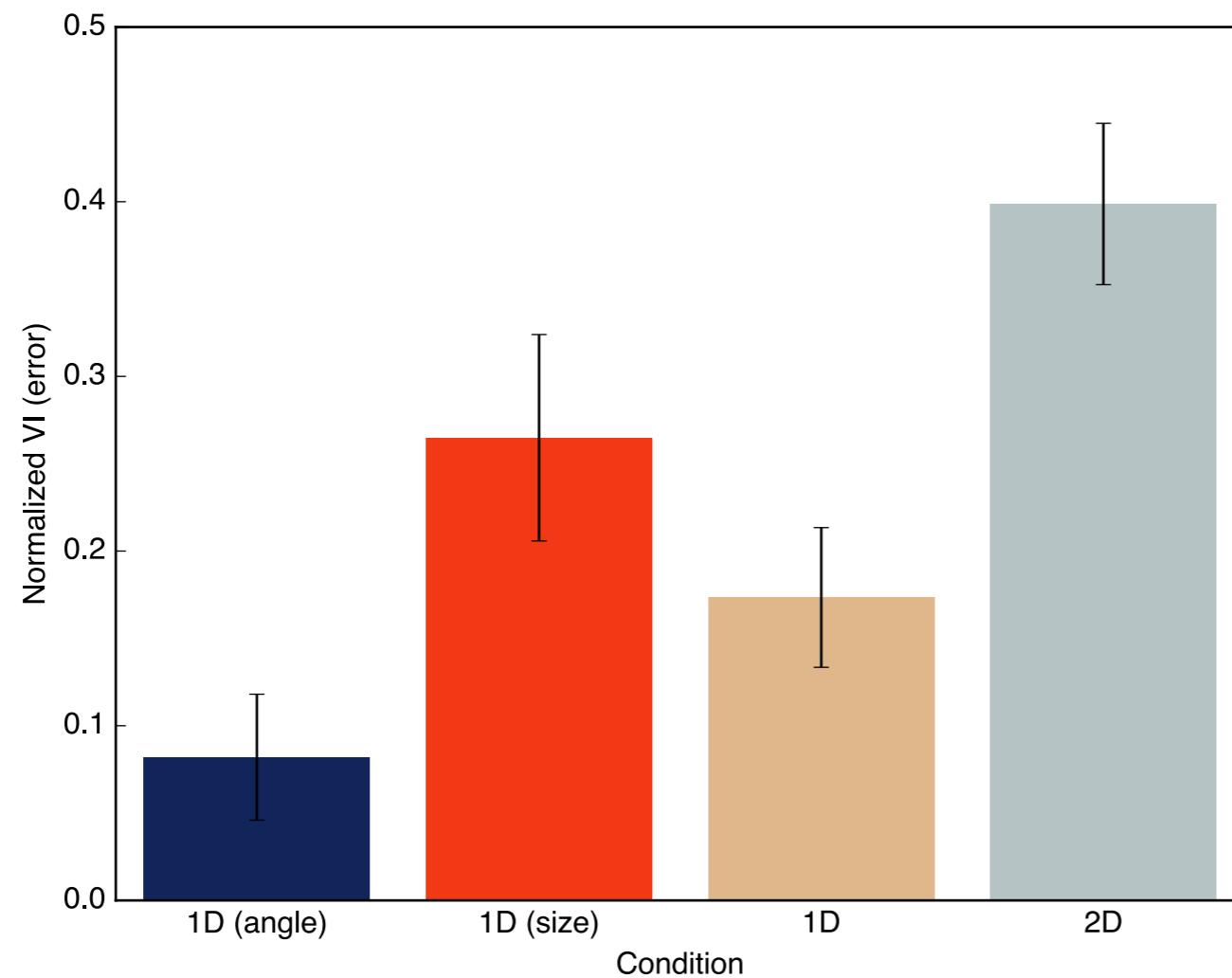
Informative but hard to learn

Results (so far. . .)

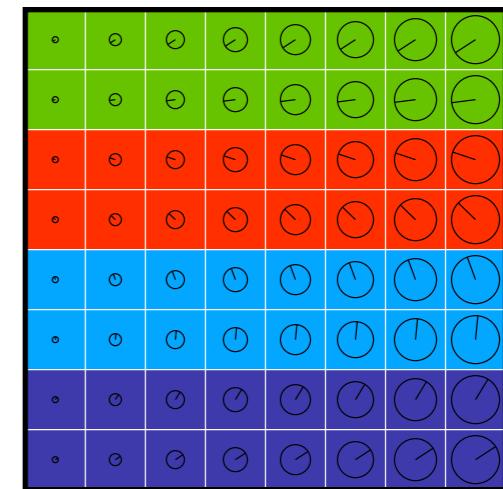
Results: Training trajectory



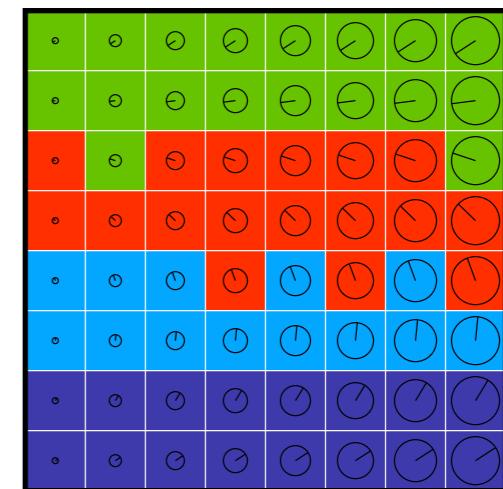
Results: Test performance



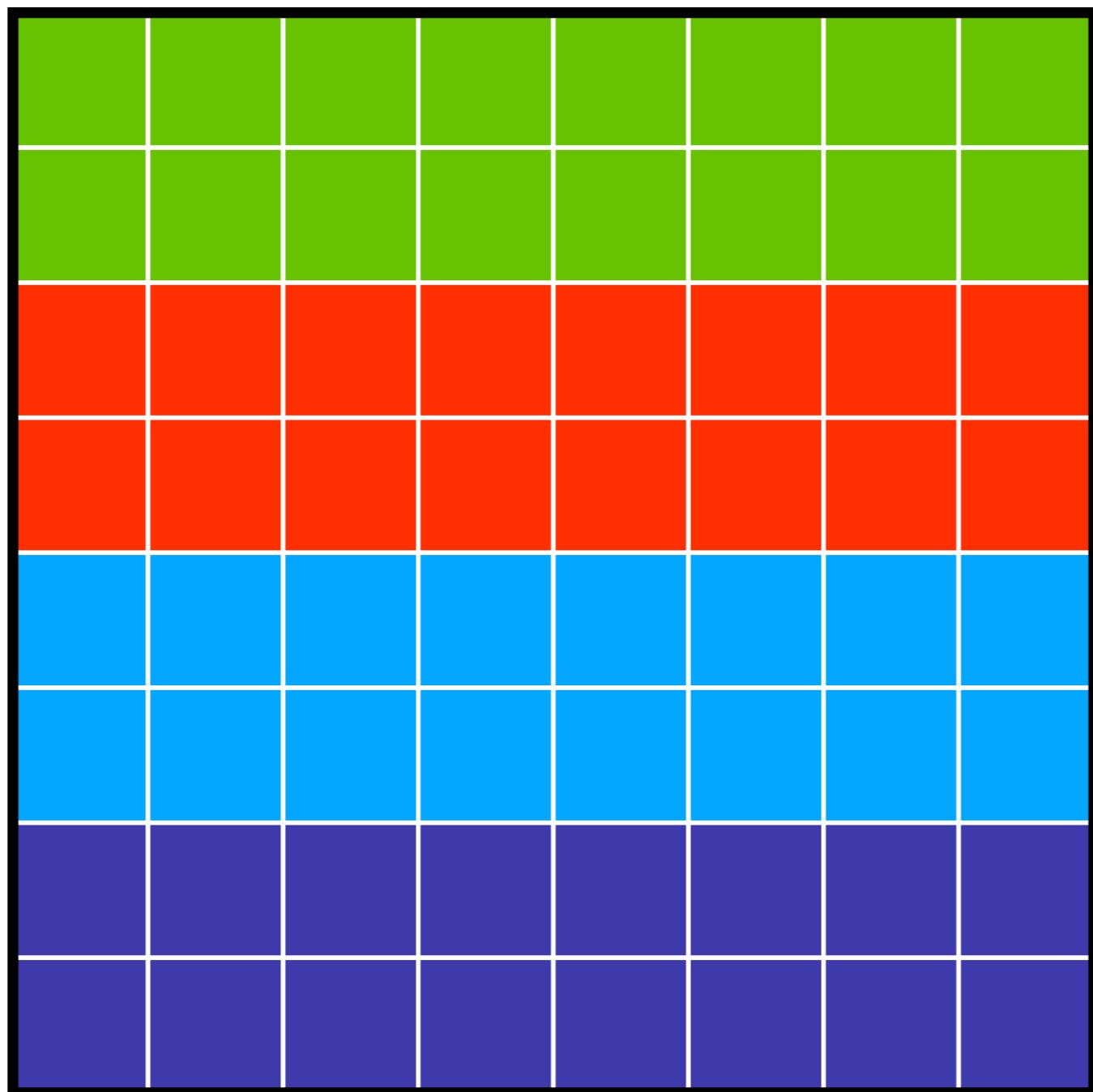
Training material



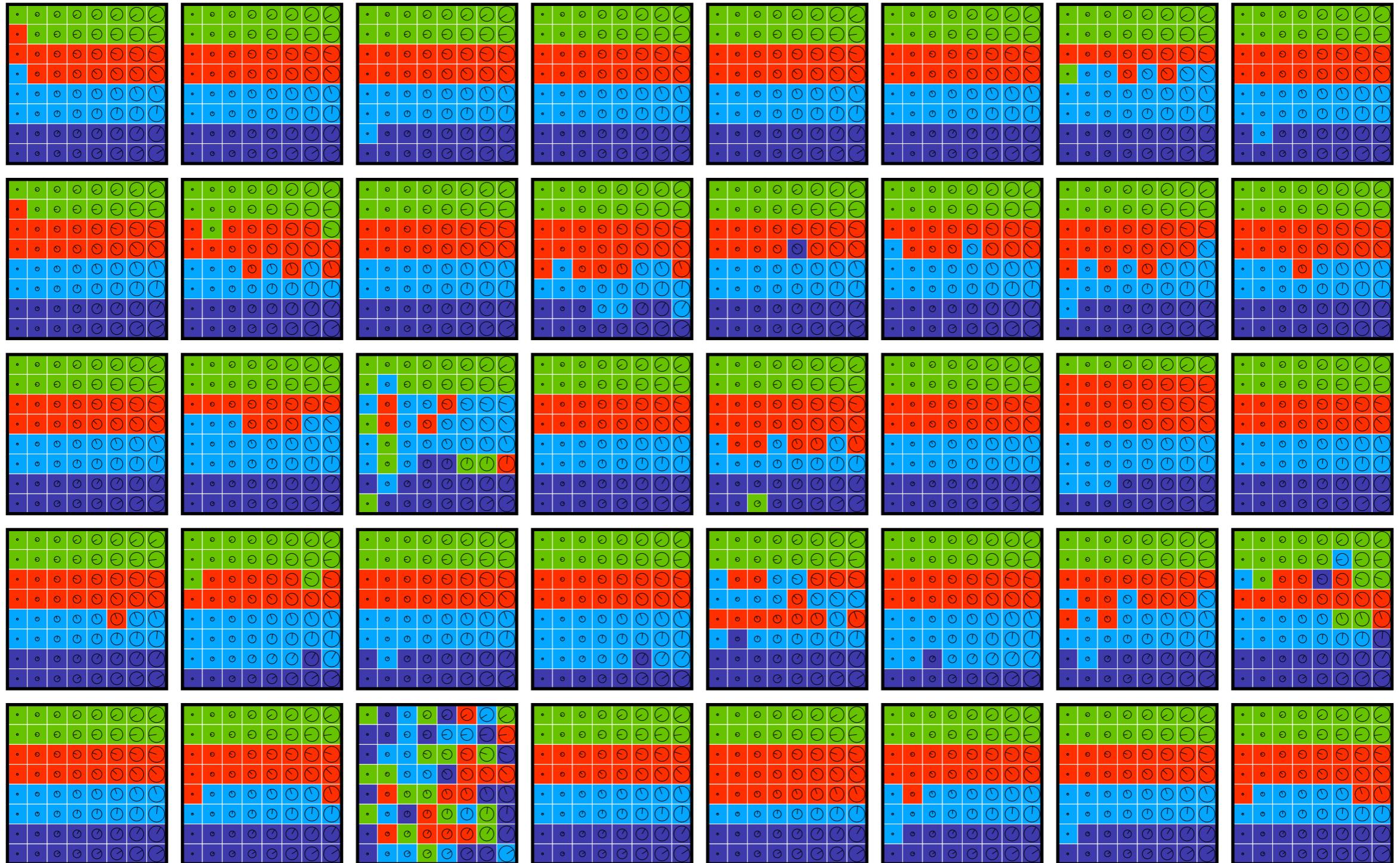
Participant's test outcome



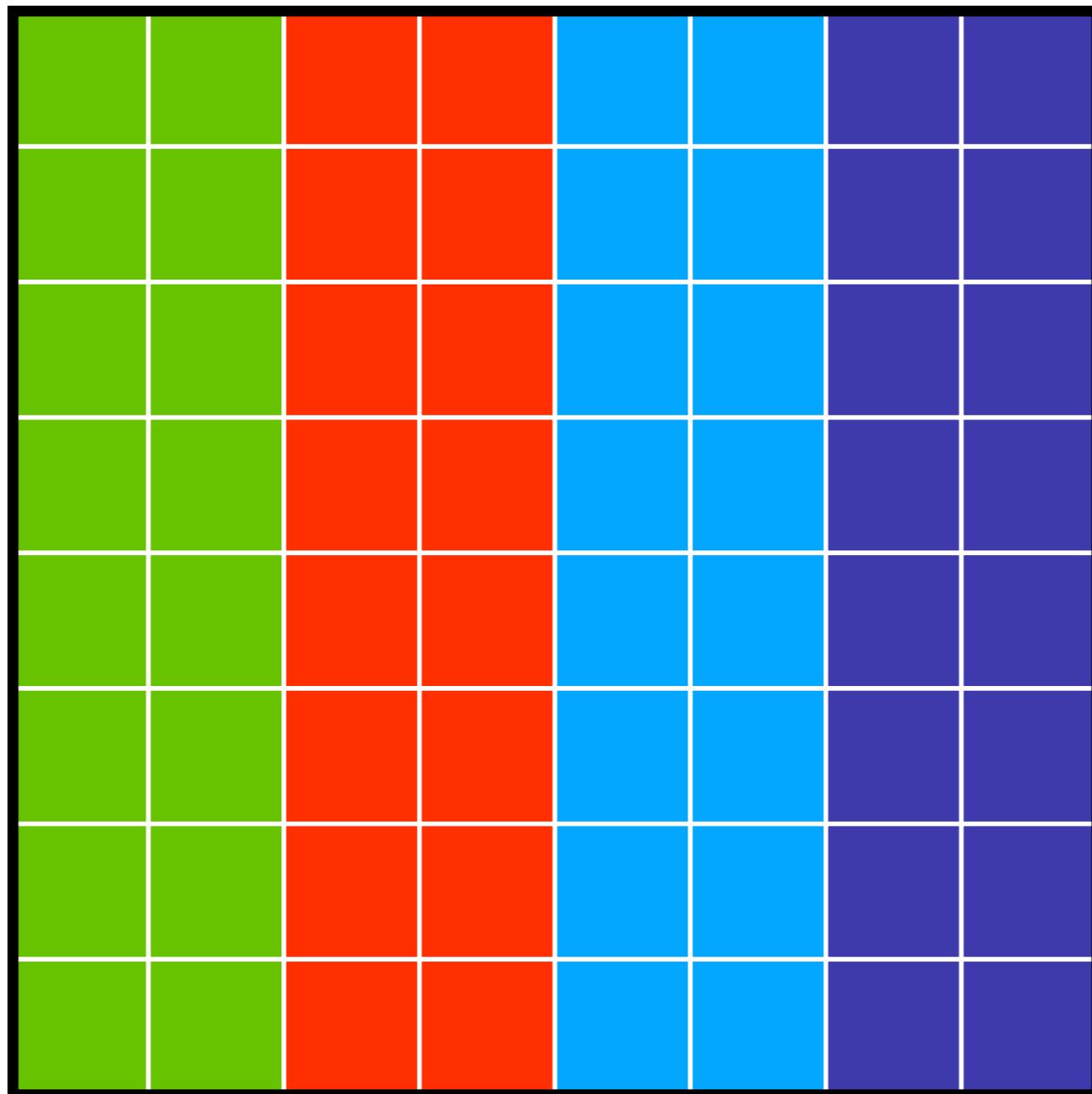
Results: Angle only



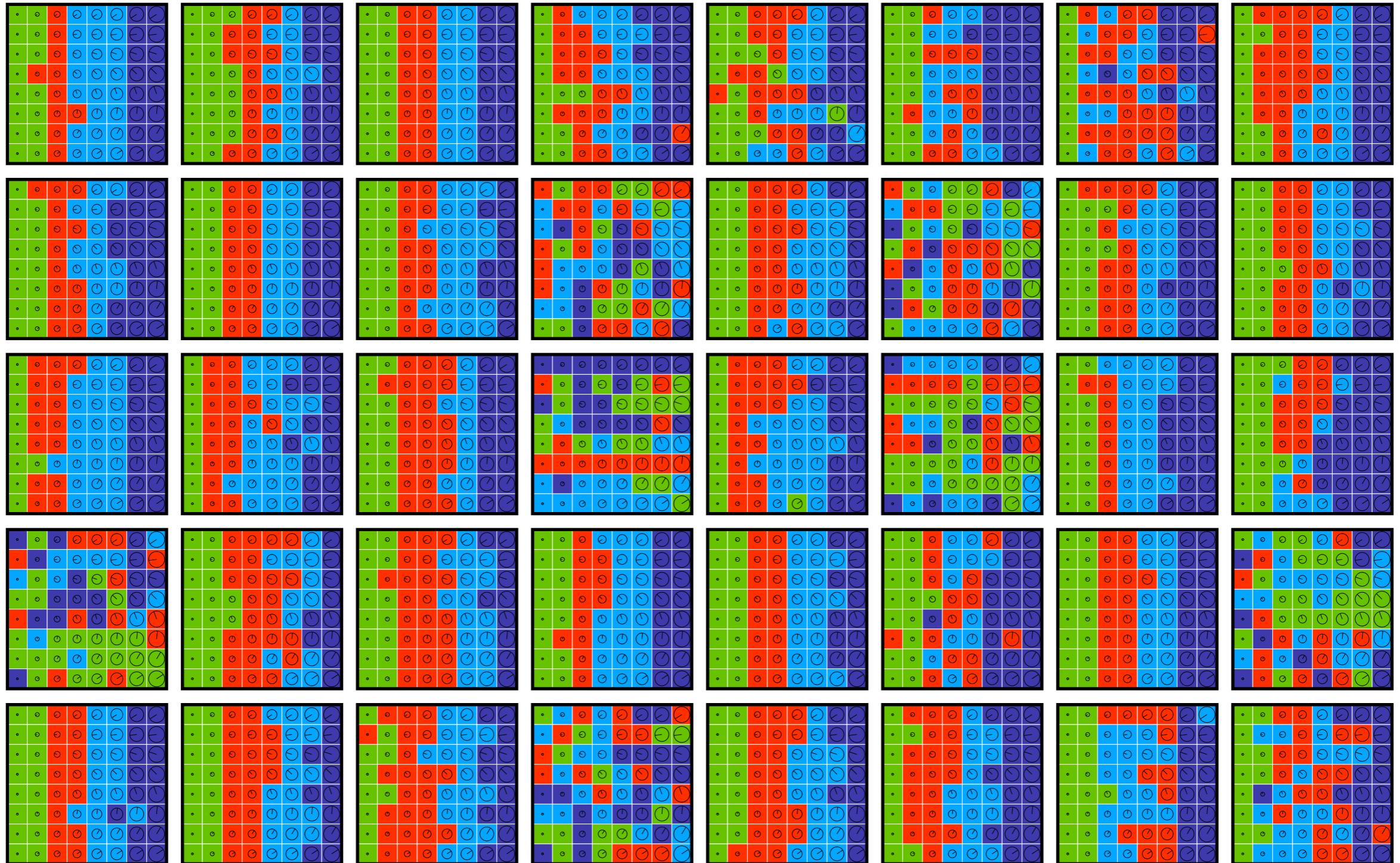
Results: Angle only



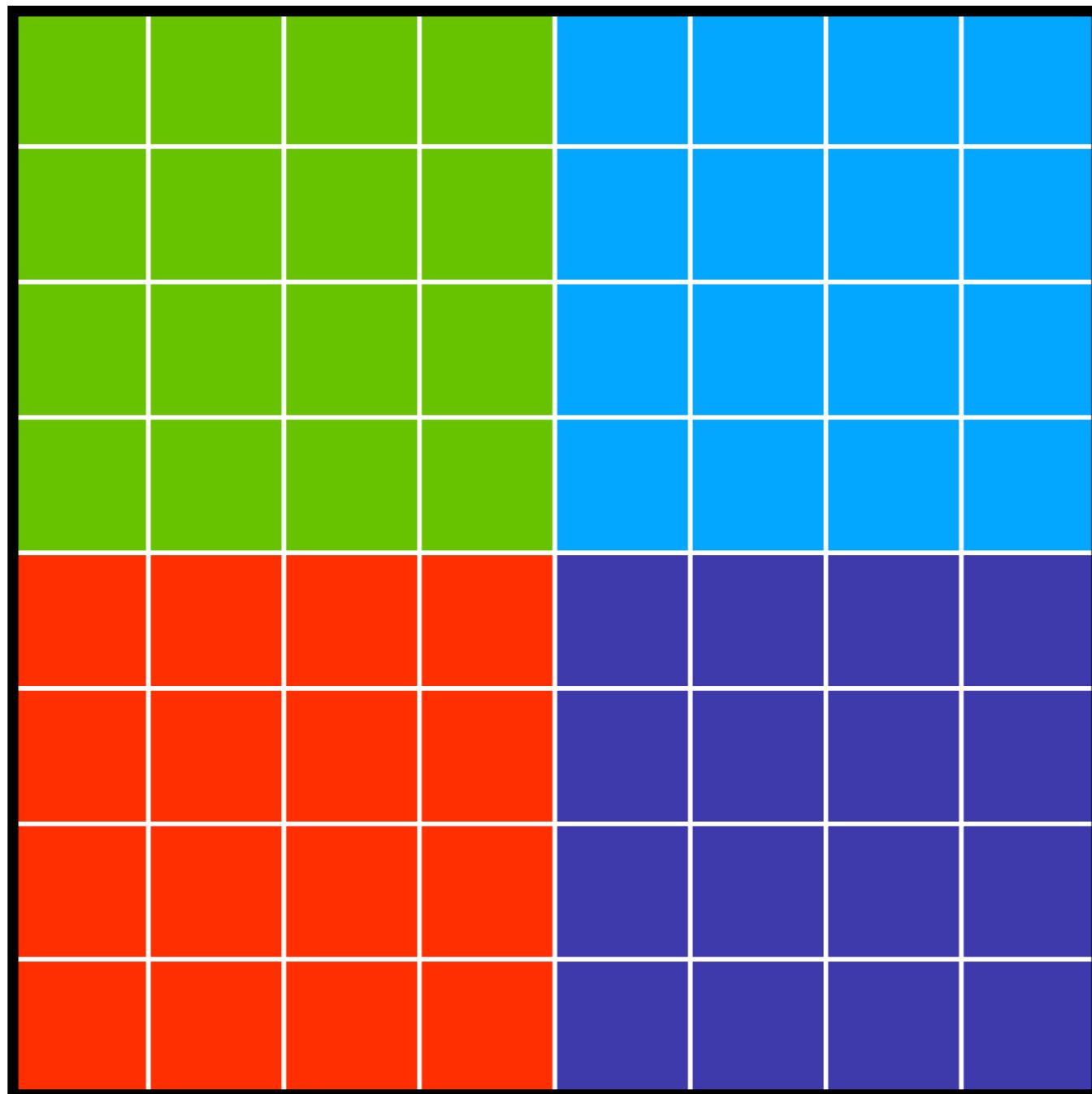
Results: Size only



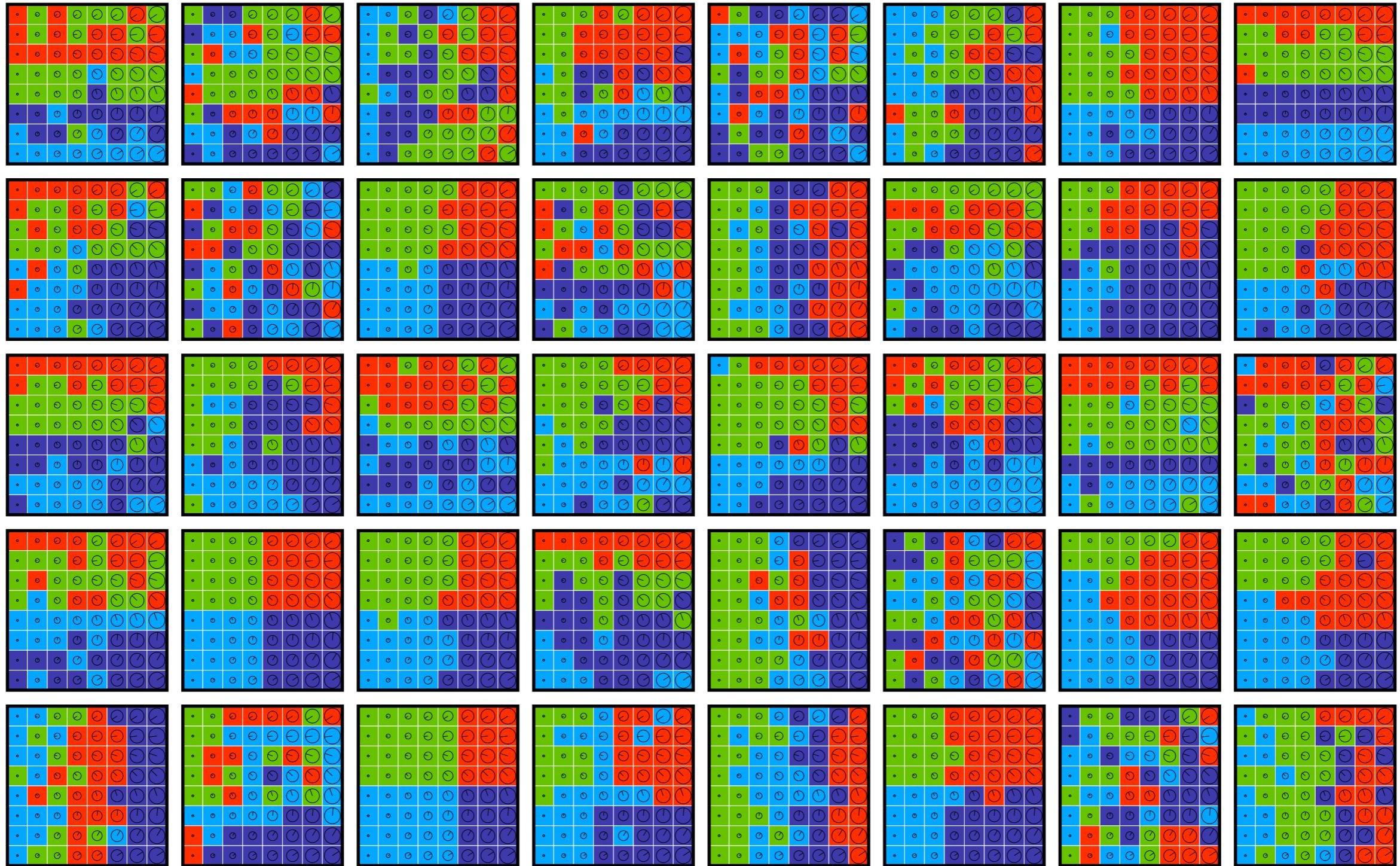
Results: Size only



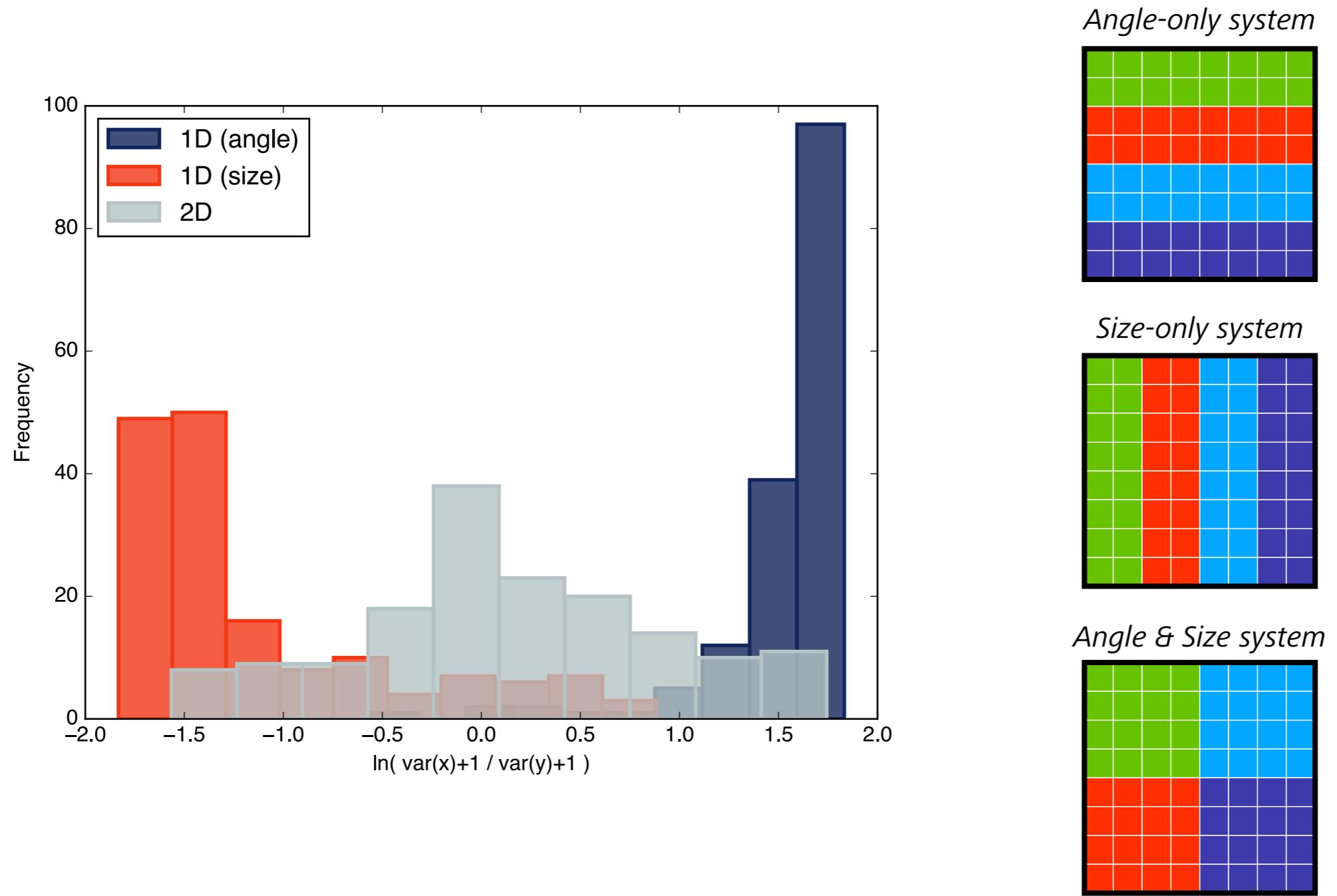
Results: Angle & Size



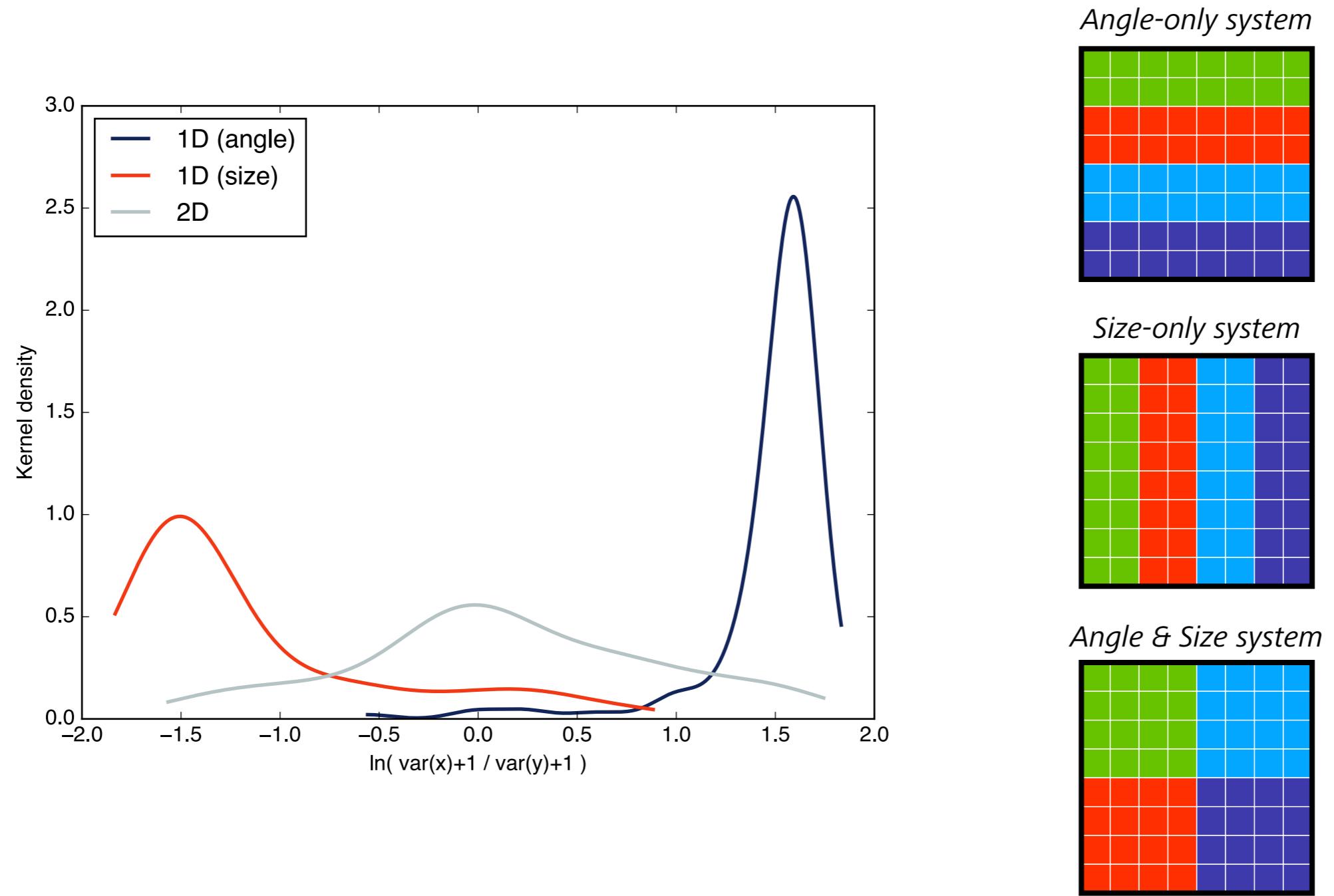
Results: Angle & Size



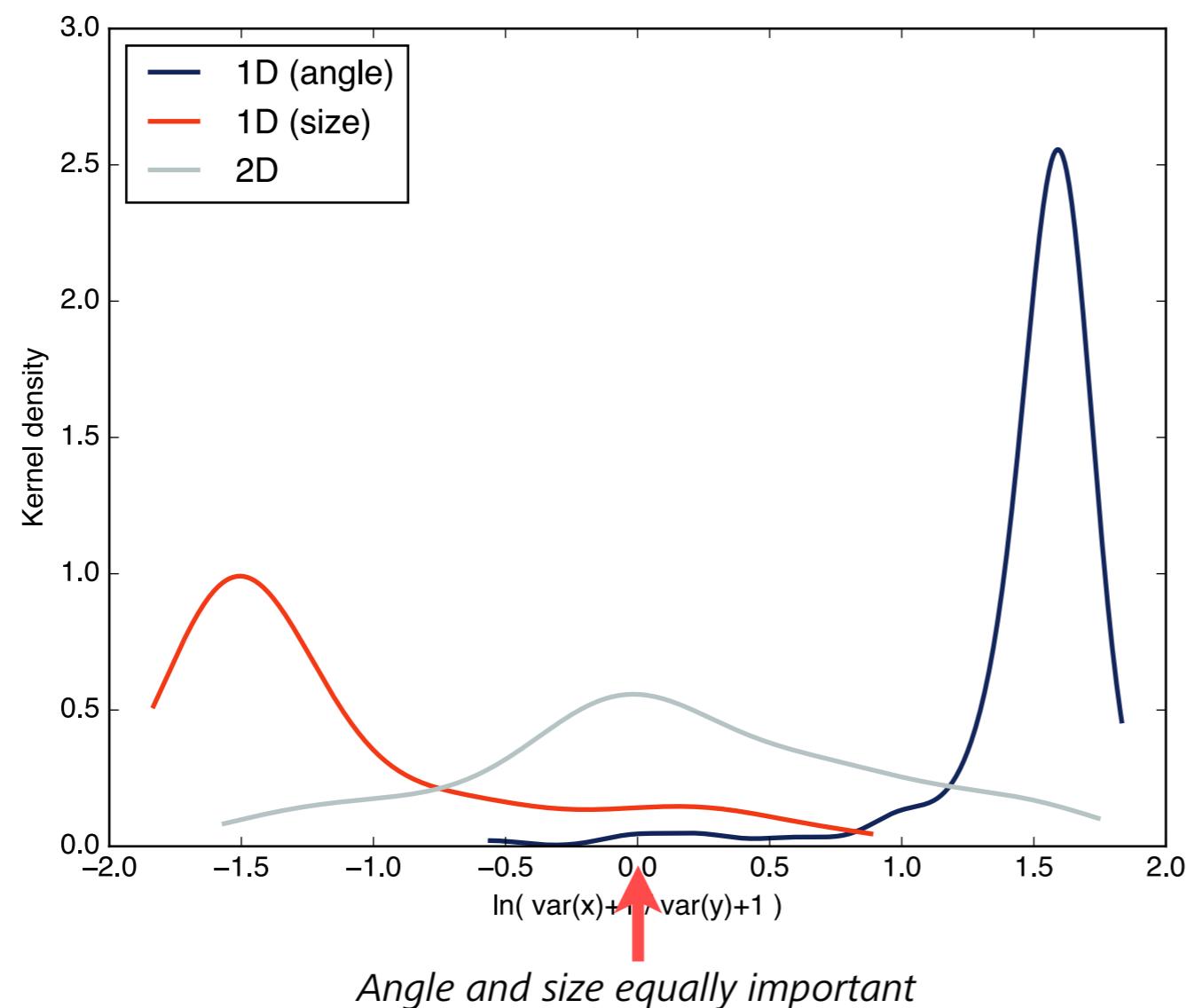
Results: Dimension preference



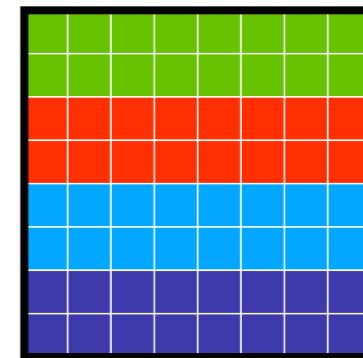
Results: Dimension preference



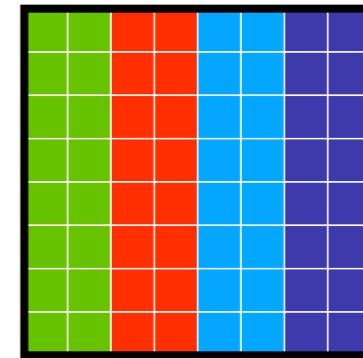
Results: Dimension preference



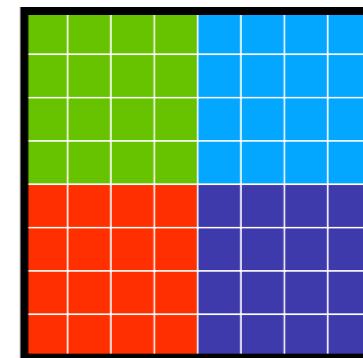
Angle-only system



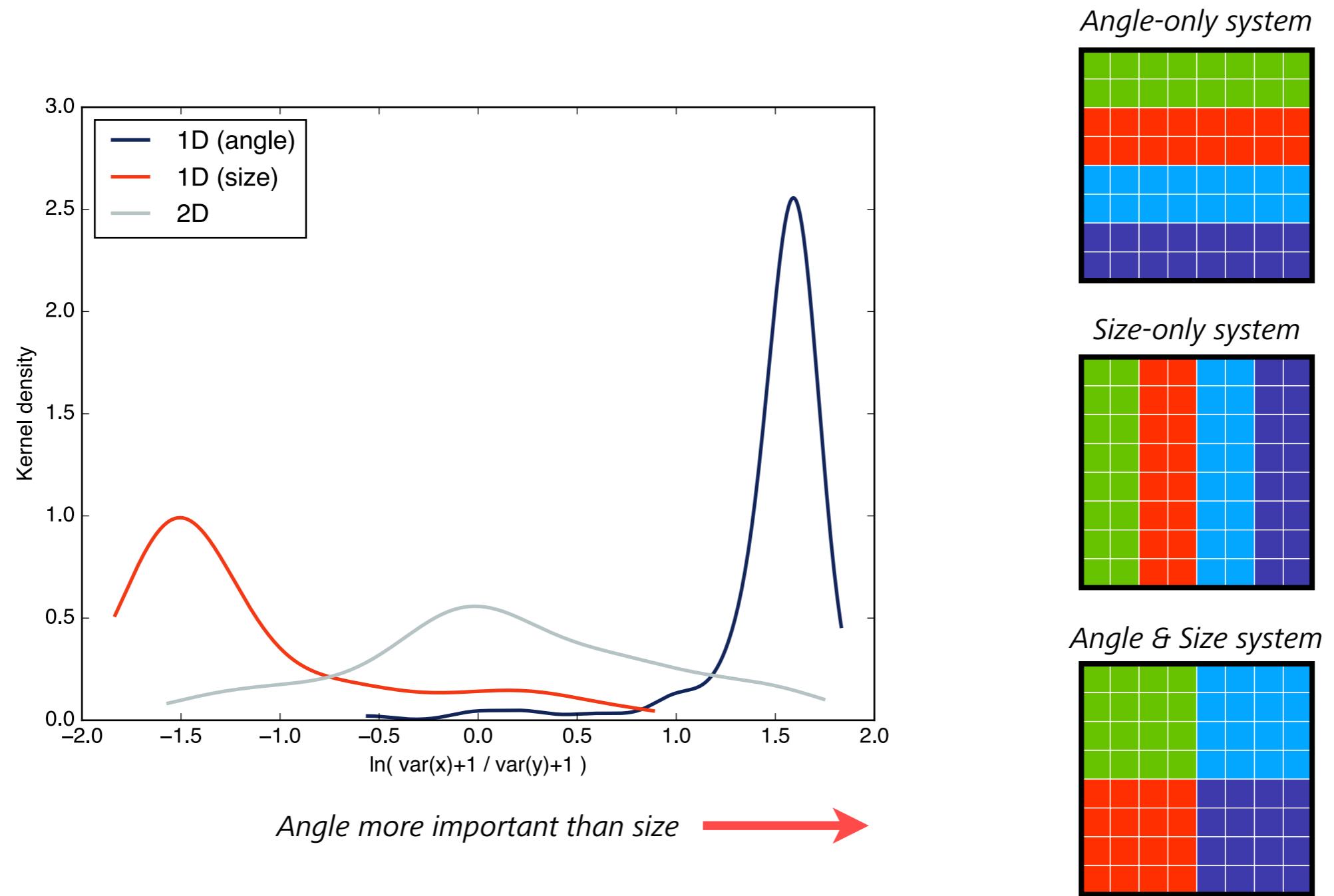
Size-only system



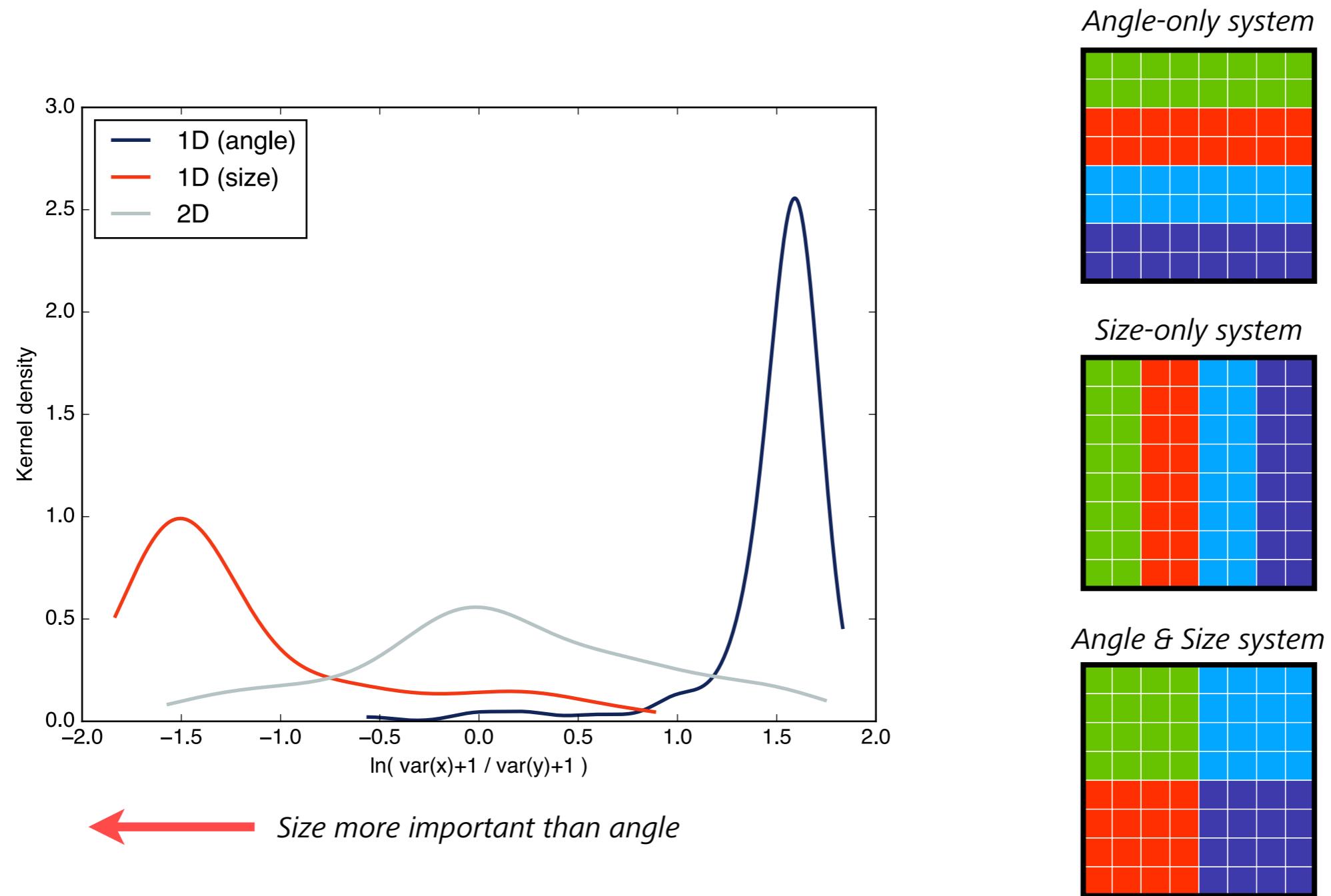
Angle & Size system



Results: Dimension preference



Results: Dimension preference



Next steps

Why do people find the size-only condition so hard – is it just something weird with these stims?

What happens when the task is iterated in a transmission chain?

Prediction: Everyone shifts to the angle-only system because it's easiest

Prediction: lots of noise

Prediction: loss of categories

What happens when you introduce a communicative task?

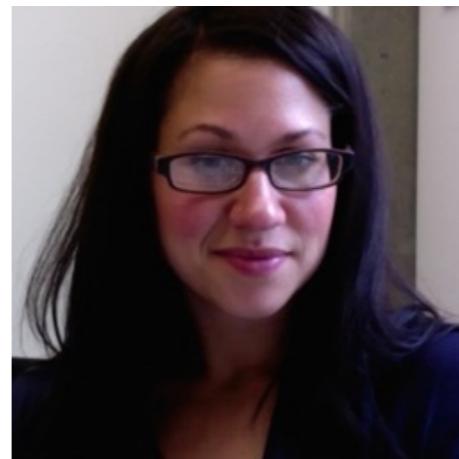
Prediction: Everyone shifts to the angle & size system because it's the most informative.



Simon Kirby



Kenny Smith



Jennifer Culbertson

Thanks!

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